Assignment 7: Lock-free approaches

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1 Stack

1.1 Background

Figure 1 shows a history for three threads. Each time line corresponds to one thread. All the threads work on a single stack s. The query s.top (i) expects an element i to be on top of stack s. Note that s.top (i) does not remove the top item. The command s.push (i) pushes an element i on top of the stack s.

00:00:00 - 00:00:03 s.push(0)			
00:00:00 - s.pus			
	00:00:03 - 00:00:05 s.top(1)	00:00:05 - 00:00:07 s.top(0)	

Figure 1: History

1.2 Task

- 1. Is the history shown in figure 1 linearizable? Justify your answer.
- 2. Is the history shown in figure 1 sequentially consistent? Justify your answer.

1.3 Solution

- 1. The history is not linearizable. The call to s.push(1) must happen before s.top(1), because s.top(1) expects an element i on top of the stack. The call to s.push(0) must not happen before the call to s.top(1) took effect. The earliest point when s.top(1) can take effect is at the start of its time span. This is however already too late for s.push(0) to take effect.
- 2. The history is sequentially consistent. An equivalent legal sequential history is given by:
 - (a) Thread $2 \operatorname{s.push}(1)$
 - (b) Thread 2 s:void
 - (c) Thread $3 \operatorname{s.top}(1)$
 - (d) Thread 3 ± 1
 - (e) Thread $1 \operatorname{s.push}(0)$
 - (f) Thread 1 s:void
 - (g) Thread $3 \operatorname{s:top}(0)$
 - (h) Thread 3 ± 0

2 Non-linearizable queue

2.1 Background

This task has been adapted from [2]. The *AtomicInteger* class is a container for an integer value. One of its methods is **boolean** compareAndSet(int expect, int update). This method compares the object's current value to expect. If the values are equal, then it atomically replaces the object's value with update and returns **true**. Otherwise, it leaves the object's value unchanged, and returns **false**. This class also provides int get() which returns the object's actual value.

Consider the following FIFO queue implementation. It stores its items in an array *items*, which, for simplicity, we will assume has unbounded size. It has two *AtomicInteger* fields. *head* is the index of the next slot from which to remove an item. *tail* is the index of the next slot in which to place an item.

```
class IQueue < T > \{
  AtomicInteger head = new AtomicInteger(0);
  AtomicInteger tail = new AtomicInteger(0);
  T[] items = (T[]) new Object[Integer.MAX_VALUE];
  public void enq(T x) {
    int slot;
    do {
      slot = tail.get();
    \mathbf{while} (! tail.compareAndSet(slot, slot + 1));
    items[slot] = x;
  }
  public T deq() throws EmptyException {
    T value;
    int slot;
    do {
      slot = head.get();
      value = items[slot];
      if (value == null) {
        throw new EmptyException();
      }
    } while (!head.compareAndSet(slot, slot + 1));
    return value;
  j
}
```

2.2 Task

Give an example showing that this implementation is not linearizable.

2.3 Solution

The problem is that the two consecutive operations tail.compareAndSet(slot, slot + 1) and items[slot] = x do not happen atomically. The problem is illustrated in the following execution.

1. Thread 1 calls q.enq(e1) with a matching element e1.

- 2. Thread 1 executes tail.compareAndSet(slot, slot + 1) and exits the loop.
- 3. Thread 2 calls q. enq(e2) with a matching element e2.
- 4. Thread 2 executes tail.compareAndSet(slot, slot + 1), exits the loop and executes *items* [slot] = x.
- 5. Thread 2 finishes the call to q. enq(e2).
- 6. Thread 3 calls q.deq().
- 7. Thread 3 executes slot = head.get() and value = items[slot]. The slot is the one set by thread 1. Note that thread 1 did not set the value for this slot yet.
- 8. Thread 3 throws an exception because *value* is **null**.
- 9. Thread 1 executes items[slot] = x.
- 10. Thread 1 finished the call to q. enq(e1).

The execution is depicted in the following history.

- 1. Thread 1 q.enq(e1)
- 2. Thread 2 q.enq(e2)
- 3. Thread 2 q:void
- 4. Thread 3 q.deq()
- 5. Thread 3 q:EmptyException()
- 6. Thread 1 q:void

The history is not linearizable. In the history above the call by thread 2 precedes the call by thread 3. This precedence relation must be preserved in any equivalent sequential history. Furthermore such a history can not have any other dequeue operations other than the one by thread 3. Therefore any such history would be invalid because a dequeue operation after a enqueue operation must not throw an empty exception in the absence of other dequeue operations.

3 Binary search tree

3.1 Background

Listing 1 shows the class of a binary search tree. The class defines a feature *insert* to add a value to a tree and a feature *has* to check whether the tree contains a value.

Listing 1: Non-linearizable binary search tree

```
class BINARY_SEARCH_TREE

2

create

4 make

6 feature -- Initialization

make (a_value: INTEGER)

8 -- Initialize this node with 'a_value'.
```

```
do
10
        left := Void
        right := Void
12
        value := a_value
      end
14
  feature -- Access
    left : BINARY_SEARCH_TREE
16
        -- The left sub tree.
    right: BINARY_SEARCH_TREE
18
        -- The right sub tree.
    value: INTEGER
20
        -- The value.
22
  feature -- Basic operations
    insert (a_new_value: INTEGER)
24
        -- Insert 'a_new_value' into the tree.
26
      require
        tree_does_not_have_new_value: not has (a_new_value)
28
      do
        if a_new_value < Current.value then
          if not left = Void then
30
            left. insert (a_new_value)
32
          else
            left := create \{BINARY\_SEARCH\_TREE\}.make (a_new\_value)
34
          end
        else
          if not right = Void then
36
            right. insert (a_new_value)
38
          else
            right := create {BINARY_SEARCH_TREE}.make (a_new_value)
40
          end
        end
42
     end
44
    has (a_value: INTEGER): BOOLEAN
        -- Does the tree have 'a_value'?
      do
46
        if a_value = Current.value then
          Result := True
48
        else
          if a_value < Current.value then
50
            if not left = Void then
              Result := left.has (a_value)
52
           else
              Result := False
54
           end
          else
56
            if not right = Void then
              Result := right.has (a_value)
58
            else
60
              Result := False
```

62 end end 64 end end

3.2 Task

- 1. Devise an execution sequence that demonstrates that the binary search tree from Listing 1 is not linearizable; provide a corresponding history and explain why this history is non-linearizable.
- 2. Using the feature *compare_and_swap*, develop a linearizable version of the binary search tree class. Provide only the changed features.

The feature *compare_and_swap* (*\$entity*, *test_value*, *new_value*) sets the value of an entity to *new_value* if and only if the entity currently has the value *test_value*; the feature call returns whether or not the test was successful. Here, the *\$* operator returns the address of the entity.

3.3 Solution

3.3.1 Task 1

Consider the following execution based on an entity n of type BINARY_SEARCH_TREE:

- 1. Thread 1: Calls create n.make (10) and finishes.
- 2. Thread 1: Calls *n. insert* (5). Continues until *left* := **create** {*BINARY_SEARCH_TREE* }.*make* (*a_new_value*).
- 3. Thread 2: Calls *n. insert* (4) and finishes.
- 4. Thread 1: Executes *left* := **create** {*BINARY_SEARCH_TREE*}.*make* (*a_new_value*). This overrides the value set by thread 2.
- 5. Thread 3: Executes n.has (4). Returns that the element could not be found.

The following history represents this execution:

- 1. Thread 1: create n.make (10)
- 2. Thread 1: n:void
- 3. Thread 1: n.insert (5)
- 4. Thread 2: n.insert (4)
- 5. Thread 2: n:void
- 6. Thread 1: n:void
- 7. Thread 3: n.has (4)
- 8. Thread 3: n:False

There are only two possible equivalent sequential histories that preserve the order relation. One of the histories lets the first thread insert its value first:

- 1. Thread 1: create n.make (10)
- 2. Thread 1: n:void
- 3. Thread 1: n.insert (5)
- 4. Thread 1: n:void
- 5. Thread 2: n.insert (4)
- 6. Thread 2: n:void
- 7. Thread 3: n.has (4)
- 8. Thread 3: n:False

The other one lets the second thread insert its value first:

- 1. Thread 1: create n.make (10)
- 2. Thread 1: n:void
- 3. Thread 2: n.insert (4)
- 4. Thread 2: n:void
- 5. Thread 1: n.insert (5)
- 6. Thread 1: n:void
- 7. Thread 3: n.has (4)
- 8. Thread 3: n:False

Both histories are illegal because the value 4 should not be reported as missing. Hence the implementation is not linearizable.

3.3.2 Task 2

Listing 2: Linearizable binary search tree

```
insert (a_new_value: INTEGER)
      -- Insert 'a_new_value' into the tree.
2
    require
4
      tree_does_not_have_new_value: not has (a_new_value)
    local
       l_cached_sub_tree : BINARY_SEARCH_TREE -- The cached sub tree.
\mathbf{6}
    do
8
      if a_new_value < Current.value then
         l_cached_sub_tree := left
        if not l_cached_sub_tree = Void then
10
          left. insert (a_new_value)
12
        else
          if not compare_and_swap ($left, l_cached_sub_tree, create {
               BINARY_SEARCH_TREE}.make (a_new_value)) then
14
             left. insert (a_new_value)
          end
16
        end
```

	else
18	$l_cached_sub_tree := right$
	if not $l_cached_sub_tree = Void then$
20	$right.insert (a_new_value)$
	else
22	if not compare_and_swap (\$right, l_cached_sub_tree, create {
	$BINARY_SEARCH_TREE$ }.make (a_new_value)) then
	$right.insert (a_new_value)$
24	end
	end
26	end
	end

The binary search tree is linearizable. When an insert operation runs in parallel to a number of insert operations, then the tree will contain the values of all these insert operations. When a has operation runs in parallel to a number of insert operations then the has operation might return true or false for the values of these insert operations. When the has operation runs after a number of insert operations then the has operation returns true for the values of these insert operations. For all other values the has operation returns false.

We now take a look at a history, by going from left to right; we look at the operations in the order in which they start. If multiple operations start at the same time, we look at these operations in a random order. As we go through the history, we construct a new sequential history, starting from an empty one.

- If the current operation is an insert operation then we add the insert operation to the end of the sequential history.
- If the current operation is a has operation that returns true for a value from an already added insert operation then we add the has operation to the end of the sequential history.
- If the current operation is a has operation that returns true for a value from a not yet added insert operation then the has operation must have run in parallel to a matching insert operation. In this case, we stall the has operation and add it after the insert operation as soon as we add the insert operation. This preserves the order relation because the insert operation ran in parallel to the has operation and hence we can choose the ordering between the two in the sequential history.
- If the current operation is a has operation that returns false and there is no insert operation that inserts this value then we add the has operation to the end of the sequential history.
- If the current operation is a has operation that returns false and there is an insert operation that inserts this value then either this insert operation must have run in parallel to the has operation or it must have run after the has operation.
 - In case the insert operation ran in parallel to the has operation, we have to distinguish two situations. One one hand, it could be that the insert operation has already been added, in which case we add the has operation in front of the insert operation. This preserves the order relation because the insert operation ran in parallel to the has operation and hence we can choose the ordering between the two in the sequential history. On the other hand, it could be that the insert operation has not been added, in which case we add the has operation to the end of the sequential history.
 - In case the insert operation ran after the has operation, we add the has operation to the end of the sequential history.

Because we add operations in the order in which they started with the only exception of operations that ran in parallel, the history produced in this way is an equivalent sequential history that preserves the order relation. The history is legal because no has operation returns true for a value that has not been added or false for a value that has been added. Hence, the binary search tree implementation is linearizable.

4 Practical sequential consistency

4.1 Background

One of the implicit simplifying assumptions behind many of the example programs presented in the course has been that sequential consistency is being followed. Recall that sequential consistency essentially means that the relative ordering of operations between threads does not have to be maintained, but the per-thread ordering of operations should be kept. However, this assumption is invalidated quite easily by both compilers and hardware without careful attention.

Compilers are free to reorder the instructions given in the program text, given that it does not change the output of the sequential program.

For example:

$$\begin{array}{ccc} 1 & a := 1 \\ b := 2 \end{array}$$

can be rewritten to

$$b := 2$$

$$2 \quad a := 1$$

if the compiler thinks it would be faster, as the output of the sequential program is the same in either case.

4.2 Task

Consider this one-shot Peterson locking algorithm:

```
enter1 := true
2 \quad turn := 2
if not enter2 or turn = 1 then
4 \quad critical \quad section
enter1 := false
```

6 **end**

How does this locking algorithm break if the compiler (or CPU) can reorder reads and writes to independent variables? To see how, it may help to rewrite the algorithm so that intermediate expressions are computed and stored into temporary variables, for example, turning a + 1 = b into

tmp1 := a + 12 tmp2 := tmp1 = b

It may also help to review the proof of mutual exclusion given in slides for lecture 3.

4.3 Solution

Because the accesses to *enter1* and *enter2* are to independent locations, these can be reordered. For the first processor (similarly for the second) the program could be rewritten as

```
tmp := not enter2

2 enter1 := true

turn := 2

4 if tmp or turn = 1 then

critical section

6 enter1 := false
```

```
end
```

Now, both processes will calculate tmp as True, since initially both entry variables are *False*. Therefore, both will enter the critical section at the same time, violating mutual exclusion.

5 Atomic update of multiple values

5.1 Background

A online game with thousands of players features a daily high score. The high score consists of the player's name and the score he or she achieved. Profiling determined that the current lock-based implementation is a bottleneck.

5.2 Task

You are asked to provide a prototype of a lock-free solution, pseudo-code is sufficient. You can use an integer for the score. Provide a routine to update the high score if the new score is better and a routine to retrieve the current high score. If you need additional data structures, describe them as well.

You are free to use the *compare_and_swap*-routine from task 3.2.

5.3 Solution

	A class providing the mechanisms for the daily high score
2	class HIGH_SCORE
	feature {NONE}
4	The name and score of the player having achieved the highest score today. A tuple is
	used to be able to set it atomically.
	data: TUPLE[name: STRING, score: INTEGER]
6	feature retrieve: TUPLE[STRING, INTEGER]
	Retrieve the name and score of the player currently having the highest score.
8	do
	Atomic retrieval of the current high score. Creating a copy to ensure changes to
	the Result are not propagated.
10	$\mathbf{Result} := data.copy$
	end
12	feature update (a_name: STRING; a_score: INTEGER)
	Checks the current high score and replaces it with the new score by the player
	named 'a_name' if 'a_score' is greater than the current high score.
14	local
	l_data , l_new_data : like data
16	<i>l_success</i> : <i>BOOLEAN</i>
	do
18	from
	$l_success := False$
20	until

	$l_success$
22	loop
	Atomic retrieval of the current high score.
24	$l_data \ := \ data$
	$l_{success} := l_{data. score} >= a_{score}$ or else
26	$compare_and_swap (data, l_data, [a_name, a_score])$
	end
28	end
	end

References

- CAS-Based Lock-Free Algorithm for Shared Deques. 9th Euro-Par Conference on Parallel Processing. Maged M. Michael 2003.
- [2] Maurice Herlihy und Nir Shavit. The Art of Multiprocessor Programming. Morgan Kaufmann, 2008.

6 Money transaction system

6.1 Background

A money transaction system handles many transactions concurrently. A status monitor displays the total turnover and total number of transactions. Updating these numbers is a sequential bottleneck and should be done as quickly as possible, hence a lock-free solution is desired. Every query of these numbers should return a consistent result, so that the accurate average can be computed.

In finance, precision is very important. This can only be guaranteed by using a big decimal type for the total turnover. A BigDecimal is not a basic type, but supports all the common operations.

In order to avoid problems with an over-eager optimizing compiler or virtual machine, all variables that are modified concurrently should be marked with the **volatile** keyword.

6.2 Task

Your task is to implement this status monitor by providing the necessary data structure(s), a method *updateTotal* to add a transaction and a method *fetchLatest* to retrieve a consistent copy of the current state.

The framework provides you with compare-and-set routines for all (basic and reference) types of variables. This routine is implemented using the atomic operations of the processor and as such is always compiled inline. The following pseudocode demonstrates its function:

boolean cas(target, oldvalue, newvalue) {

```
// target, oldvalue and newvalue have to be of the same type.
synchronized {
    if (target == oldvalue) {
        // This change is propagated outside the current scope.
        target = newvalue;
        return true;
    }
    return false;
}
```

6.3 Solution

}

```
public class TransactionsTotal {
    volatile TransactionsTotalData \ data = new \ TransactionsTotalData();
    class Transactions TotalData {
        long transactions;
        BigDecimal turnover;
    }
}
public class TransactionAgent {
    private TransactionsTotal total;
    //Called at the end of a transaction
    protected void updateTotal (BigDecimal turnover) {
        //Update total by adding a transaction with the given turnover
        do {
            Transactions TotalData \ old = counter.data;
            Transactions TotalData \ data = new \ Transactions TotalData();
            data. transactions = old. transactions + 1;
            data.turnover = old.turnover + turnover;
        } while (!cas (counter.data, old, data));
    }
}
//Class to fetch current transactions total
public class TransactionsTotalFetcher {
    // The following two variables are used to store the retrieved total after calling
    // fetchLatest()
    private long transactions;
    private BigDecimal turnover;
    private TransactionsTotal total;
    //Return the number of transactions
    public long getTransactions() {
        return transactions;
    }
    public BigDecimal getTurnover() {
        return turnover;
    }
    public void fetchLatest() {
        //Update attributes to match current state
        CounterData \ data = counter.data;
        transactions = data.transactions;
        turnover = data.turnover;
    }
```