



Concepts of Concurrent Computation

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Lecture 9: Languages for Concurrency & Parallelism

In this lecture you will learn about:

- How to classify various approaches to concurrency in programming languages
- A number of message passing approaches to concurrency: Ada, Erlang (Actor model), Message passing interface (MPI), ...
- A number of shared memory approaches to concurrency: OpenMP, Linda (Coordination languages), Cilk, ...



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Classification

Concurrent and parallel languages

Developers today have the choice among a multitude of different approaches to concurrent and parallel programming





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Message passing approaches

Asynchronous communication

- Asynchronous: the sender sends a message and continues, regardless of whether the message has been received
- Requires buffer space
- Analogy: Email



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Synchronous communication

- Synchronous: the sender blocks until the receiver is ready to receive the message
- Analogy: Phone call





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Ada

- Object-oriented language, influenced by Pascal, developed from 1975 by US Department of Defence, standards: Ada83, Ada95, Ada 2005
- Design goals: highly reliable systems, reusable components, concurrency part of the language
- Named after Ada Lovelace (1815-1852), "the first computer programmer"
- Supports concurrent execution via *tasks*, which can have *entries* for synchronous message-passing communication
- Ada also offers shared memory synchronization via protected objects, a monitor-like mechanism where condition variables are replaced with guards

Ada Tasks

- Tasks are declared within procedures
- Two parts: task specification, task implementation
- Tasks are activated when the procedure starts executing

```
procedure SimpleProc is
   task type SimpleTask;
   task body SimpleTask is
   begin
   end SimpleTask;
   taskA, taskB: SimpleTask;
begin
   null;
end SimpleProc;
```

Process communication: Rendezvous (1)

- Uses synchronous communication, called the "rendezvous"
- Entry points (declared in the type declaration) specify the actions a task can synchronize on

task type SimpleTask is
 entry MyEntry;
end SimpleTask;

Process communication: Rendezvous (2)

- accept-statements (within the task body) indicate program points where rendezvous can take place
- Clients invoke an entry point to initiate a rendezvous, and wait for the accepting task to reach a corresponding entry point

```
task body SimpleTask is<br/>begin<br/>accept MyEntry do<br/>-- body of rendezvous<br/>end MyEntry;<br/>...declare<br/>T: SimpleTask;<br/>begin<br/>...<br/>T.MyEntry;<br/>-- wait until T reaches MyEntry<br/>...<br/>end SimpleTask;
```

 Upon establishing a rendezvous, the client waits for the accepting task to execute the body of the rendezvous and resumes afterward

Process communication: Rendezvous (3)

• Entry points can have parameters to pass on values

```
accept append(x : in integer) do
...
end append;
```

buffer.append(item);

- select-statement allows for waiting for multiple entries
- Within a select, alternatives may be guarded by boolean expressions
- Only if the guard evaluates to true the acceptstatement is permitted

```
select
when count < n =>
    accept append(x : in integer) do
    ...
end append;
or
when ...
```

Example: Producer-Consumer problem in Ada

```
task body Buffer is
  count, in, out: integer := 0;
  buff: array(0..n-1) of integer;
begin
  loop
    select
       when count < n =>
         accept append(x : in integer) do
            buff(in) := x;
         end append;
       in := (in - 1) mod n; count := count + 1;
    or
       when count > 0 =>
         accept remove(y : out integer) do
            y := buff(out);
         end remove:
       out := (out + 1) mod n; count := count - 1;
    end select:
  end loop;
end buffer;
```

Protected objects

- Monitor-like concept:
 - All data private
 - Exports only procedures, functions, and entries
- *Functions* may only read data, therefore multiple function calls may be active on the same object
- Procedures and entries may read and write data, and exclude other procedures and functions
- Invocation of entries with guards, similar to Hoare's conditional critical regions

Conditional critical regions

- Conditional critical regions provide condition synchronization without condition variables
- If S is a critical region for variable x, then the following is a conditional critical region with guard B:

region x when B do S

- If a process wants to enter a conditional critical region, it must obtain the mutex lock or is queued otherwise.
- When the lock is acquired, the boolean expression B is tested. If B evaluates to true, the process proceeds into the critical region. Otherwise it releases the lock and is queued. Upon reacquisition of the lock, the process must retest B.

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Example: Protected objects

protected type Semaphore is
 entry Down;
 procedure Up;
 function Get_Count return Natural;
 private
 Count: Natural := 0;
 end Semaphore;

protected body Semaphore is

```
entry Down when Count > 0 is
begin
    Count := Count - 1;
end Down;
procedure Up is
begin
    Count := Count + 1;
end Up;
function Get_Count return Natural is
begin
    return Count;
end Count;
end Semaphore;
```

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Ada: Discussion

- One of the first languages to introduce high-level concurrency constructs into the language
- Both message passing and shared memory concepts available: good to fit the approach to the problem at hand and performance requirements
- Ada is still actively developed



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The Actor model: Erlang

• A mathematical model of concurrent computation, introduced by (Hewitt, 1973) and refined by (Agha, 1985) and others

- Actor metaphor: "active agent which plays a role on cue according to a script"
- Process communication through asynchronous message passing
- No shared state between actors

• An *actor* is an entity which in response to a message it receives can

- send finitely many messages to other actors
- determine new behavior for messages it receives in the future
- create a finite set of new actors
- Communication via asynchronous message passing
- Recipients of messages are identified by addresses, hence an actor can only communicate with actors whose addresses it has
- A *message* consists of
 - the target to whom the communication is addressed
 - the content of the message

- *Erlang*: functional language, developed by Ericsson since 1986
- Erlang implements the Actor model

Erlang syntax for concurrency

When processes (≈ actors) are created using spawn, they are given unique process identifiers (or PIDs)
 PID = spawn(Module, Function, Arguments)

 Messages are sent by passing tuples to a PID with the ! syntax.

PID ! {message}.

Messages are retrieved from the mailbox using the receive() function with pattern matching receive

```
Message1 -> Actions1 ;
Message2 -> Actions2 ;
```

end

...

Example: A simple counter

```
Interface

start() ->

spawn(counter, counter_loop, [0]).

increment(Counter) ->

Counter ! inc.

value(Counter) ->

Counter ! {self(),value},

receive

{Counter,Value} -> Value

end.
```

Counter counter_loop(Val) -> receive inc -> counter_loop(Val + 1); {From,value} -> From ! {self(),Val}, counter_loop(Val); Other -> counter_loop(Val) end.

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Actors: Discussion

- Influential model for asynchronous message passing
- Also implemented in various other languages, e.g. Scala and Axum (Microsoft)
- Success story: Ericsson AXD301 switch for telecommunication systems with very high reliability – more than one million lines of Erlang



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Message Passing Interface (MPI)

Message Passing Interface (MPI)

- Message Passing Interface (MPI): API specification for process communication via messages, developed in 1993-94
- For parallel programs on distributed memory systems

"Hello, World!" in MPI

- Processes involved in an MPI execution are identified by ranks, i.e. integer numbers 0, 1, ..., numproc - 1
- In the following program, Process O gets and prints messages from all other processes

```
MPI_Init(&argc,&argv); // Initialize MPI
MPI_Comm_rank(MPI_COMM_WORLD, &my_rank); // My identifier
MPI_Comm_size(MPI_COMM_WORLD, &numproc); // Total number of processes
if (my_rank != 0) {
    sprintf(message, "Greetings from process %d!", my_rank);
    dest = 0;
    MPI_Send(message, strlen(message)+1, MPI_CHAR, dest, tag, MPI_COMM_WORLD);
    } else {
      for (source = 1; source < numproc; source++) {
           MPI_Recv(message, sizeof(message), MPI_CHAR,
            source, tag, MPI_COMM_WORLD, &status);
            printf("%s\n", message);
      }
      MPI_Finalize(); // Shut down MPI
```

SPMD in **MPI**

- As seen in the previous program, the most common paradigm used in MPI is SPMD
- Within each process, we take branches based on its rank
- At startup, processes are mapped to processors by the MPI runtime

MPI: Discussion

- Dominant model used in high-performance computing
- Good portability: implemented for many distributed memory architectures
- Available as library in many languages, in particular Fortran, C, C++



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Polyphonic C#

(Based on slides by C.A. Furia)

Polyphonic C#

• Polyphonic C# is an extension of C# with a few high-level primitives for concurrency, appeared in 2004

- Based on join calculus (Fournet & Gonthier, 1996)
- Taken up by Microsoft's Cw project
- JoinJava is a similar extension for Java
- Based on two basic notions
 - Asynchronous methods
 - Chords





Asynchronous methods

- Calls to asynchronous methods return immediately without returning any result:
 - The callee is scheduled for execution in a different thread
 - Similar to sending a message or raising an event
 - Declared using async keyword instead of void

```
public async startComputation () {
    // computation
}
```

Aynchronous methods do not return any value

A *chord* extends the notion of a method definition:

- The signature of a chord is a collection of (traditional) method declarations joined by &
- The body of a chord is all similar to the body of a traditional method

```
public String get() & public async put(String i) {
    return i;
}
```

- Within a chord at most one method can be non-async
- Within a class the same method can appear in more than one chord

- A chord is only executed once all the methods in its signature have been called:
 - Calls are buffered until there is a matching chord
 - the implicit buffer supports complex synchronization patterns with little code (see Producer/Consumer later)
 - If multiple matches are possible, nondeterminism applies
 - Execution returns a value to the only nonasynchronous method in the chord (if any)

```
public class Buffer() {
        public String get() & public async put(String i) {
               return i:
        }
}
Buffer b = new Buffer();
b.put("A")
Console.WriteLine(b.get()); // prints "A"
b.put("A"); b.put("B");
Console.WriteLine(b.get() + b.get()); // prints "AB"
b.get(); // blocks until some other thread calls put
```
Polyphonic C#: Discussion

- Combination of two ideas: asynchronous methods and chords
- Asynchronous methods also appear in earlier languages such as Cilk
- Chords: novel idea for message passing communication among more than two threads
- Cw project is discontinued



Shared Memory Approaches





(Some slides adapted from Intel teaching material)

OpenMP

 OpenMP (Open Multi-Processing) API for shared memory multithreaded programming, appeared in 1997



• Using preprocessor directives (pragmas) to mark parallel code, may be ignored by other compilers

#pragma omp construct [clause [clause]...]

Programming model

- Fork-join parallelism:
 - Master thread spawns a team of threads as needed
 - Parallelism is added incrementally: that is, the sequential program evolves into a parallel program



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Work sharing: data parallelism

- parallel construct forks additional threads
- for and do constructs distribute loop iterations within the threads that encounter the construct

```
// assume N = 100000
#pragma omp parallel
{
    #pragma omp for
    {
      for(i = 0, i < N, i++)
          c[i] = a[i] + b[i];
    }
}</pre>
```



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Work sharing: task parallelism

 The sections construct can be used to compute tasks in parallel

```
#pragma omp parallel sections
#pragma omp section /* Optional */
  a = taskA();
#pragma omp section
  b = taskB();
#pragma omp section
  c = taskC();
x = combine(a, b);
y = combine(x, c);
```



OpenMP clauses

- OpenMP constructs can be further refined by clauses
- private: make variables local to each thread (shared by default)
- critical section: the enclosed block is executed by at most one thread at a time
- schedule(type, chunk): define the type of scheduling used for work sharing
 - type static: divide work equally between threads (each gets chunk iterations)
 - type dynamic: threads may request more iterations when finished (for load balancing)
 - type guided: chunk size decreases exponentially, but won't be smaller than *chunk*

OpenMP: Discussion

- Library approach, no language integration
- Implemented for C, C++, Fortran, available on many platforms
- Supports incremental development of parallel programs, starting with a sequential one
- Some support for load balancing



Coordination Languages: Linda

- Coordination languages are based on the assumption that a concurrent programming language has two parts:
 - A *computation language*, in which single-threaded execution is defined
 - A *coordination language*, for creation of computations and process communication
- The coordination features are based on the idea of a tuple space, which holds data tuples that can be stored and retrieved by the processes
- Linda is the original coordination language, appeared around 1985

Tuple spaces

- A *tuple space* is a collection of tuples such as {("test", 11, true), ("test", 3, false), ("b", 23), ... }
- Tuple spaces can be read and modified via the following operations:
 - $out(a_1, ..., a_n)$ write tuple

 - eval(P)

• $in(a_1, ..., a_n)$ read and remove matching tuple

- read(a₁, ..., a_n) read matching tuple
 - start a new process P
- Pattern matching for in and read:
 - (a_1, \dots, a_n) can contain both actual and formal parameters
 - If no matching tuple is found, the operation blocks

Example: Tuple spaces

- Assume we have the following tuple space: {("test", 11, true), ("test", 3, false), ("b", 23)}
- Operations:
 - in("a", x) blocks, no matching tuple
 - in("test", x, b) removes tuple ("test", 11, true) and binds 11 to x and true to b (could have also selected tuple ("test", 3, false))
 - read("test", x, b) reads tuple ("test", 3, false)
 - out("a", 14) puts ("a", 14) into the tuple space
 - The last action unblocks in("a", x), which will remove the inserted tuple

Simulating semaphores in Linda

- Semaphores can be implemented in Linda
 - Initilization: tuple space with k tuples ("token")
 - Implement *down* with in("token")
 - Implement up with out("token")
- Solution to the mutual exclusion problem:

while true do

in("token")
critical section
out("token")
non-critical section
end

Linda: Discussion

- Communicating processes in Linda are only *loosely coupled*, processes need not know about other processes
- The coordination language is completely orthogonal to computation
 - Distribution of processes is easy
 - Potentially processes written in different languages can cooperate
- Implementations of Linda can be found in several languages such as Java (JavaSpaces) and C



Cilk

- Cilk is a language extension to C/C++, appeared in 1994
- For shared-memory multiprocessing

Cilk keywords

- Cilk extends C/C++ with only few keywords:
 - cilk: the routine may be spawned off in parallel
 - spawn: the routine may execute in parallel with the parent caller
 - sync: wait until all child threads have returned

```
cilk int fib (int n)
{
    if (n < 2) return n;
    else
      {
        int x, y;
        x = spawn fib (n-1);
        y = fib (n-2);
        sync;
        return (x+y);
    }
}</pre>
```

Work stealing

- Each processor maintains a queue of threads that are ready to execute
- If the queue of a processor is empty, the processor may steal threads from a random processor's queue

Cilk: Discussion

- Programmer indicates what can be executed in parallel
- The runtime environment decides how the work is divided among processors
- Hence it is automatic to map Cilk programs to new architectures
- When removing all Cilk keywords from a Cilk program, the result is a valid serial C program
- Cilk is commercially implemented and distributed by Intel

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Partitioned global address space (PGAS) model

- Each processor has its own local memory, but the address space is unified
- This allows processes on other processors to access remote data via simple assignment or dereference operations



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- Object-oriented language based on the PGAS model, appeared in 2004, developed by IBM
- New threads can be spawned asynchronously: Asynchronous PGAS model
- A memory partition and the threads operating on it are called a *place*

- async S
 - Asynchronously spawns a new child thread executing S and returns immediately
- finish S
 - Executes S and waits until all asynchronously spawned child threads have terminated

```
def fib(n: int): int {
    if (n < 2) return 1;
    val n1: int;
    val n2: int;
    finish {
        async n1 = fib(n - 1);
        n2 = fib(n - 2);
    }
    return n1 + n2;
}</pre>
```

- when (E) S
 - Conditional critical region: suspends the thread until E is true, then executes S atomically
 - E must be nonblocking, sequential, only access local data, and be side-effect free



X10: Discussion

- Developed as part of the High Productivity Computing Systems initiative of the US Department of Defense: novel languages for supercomputing
- Very similar (in the same project):
 - Chapel, developed by Cray
 - Fortress (Fortran-based)
- More traditional PGAS languages:
 - UPC (Unified Parallel C)
 - Co-array Fortran
 - Titanium (Java extension)

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