



Robotics Programming Laboratory

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Lecture 1:

Introduction to robotics Introduction to software engineering After completing this laboratory course, you will understand:

Basic software engineering principles and methods
 Most common architectures in robotics
 Coordination and synchronization methods
 How software engineering applies to robotics

and have gained experience in programming a small robotics system

Practical details

Lecturers Prof. Dr. Bertrand Meyer Dr. Jiwon Shin Assistants Andrey Rusakov Ganesh Ramanathan Course page <u>http://se.inf.ethz.ch/courses/2015b_fall/rpl</u> Forum

<u>https://piazza.com/class/idbqs3jsxfn6zn</u>

Practical details

Schedule
Monday, 16:15 – 18:00, WEH D 4
Thursday, 15:15 – 17:00, WEH D 4

This is a hands-on laboratory class. You will develop software for your own robot. Lectures and exercise sessions will be much more interactive than in traditional courses.

Your fellow classmates are your best resources. We encourage you to talk to each other and help each other. For online communication, use the forum to post your questions and answer questions other have.

Practical details

Laboratory space

- WEH D 4 is open exclusively to you.
- In a week, you can pick up keys to the building and to the room.
- Please lock the room when you leave and close the main door when you enter and leave.
- Please keep the space tidy!

Hardware

- Starting next Monday, you can get a robot, a sensor, and some cables to be used for the class.
- We ask you to deposit 50 CHF for the hardware. You will get the money back when you return the hardware.
- We expect you to have a laptop. If you do not have one, please contact us.

Grading

The grade for this laboratory course is based **entirely on the project**. Every assignment has an individual component (50%) and a group component (50%). For the group portion, you may work in a group of 2 to 3 people.

You must submit your work at every evaluation point and participate in the final competition to receive a grade for this class. You must pass both individual component and group component to pass this course.

- Assignment 1 (8 Oct/19 Oct): control and obstacle avoidance
- Assignment 2 (3 Nov/9 Nov): path planning
- Assignment 3 (23 Nov/30 Nov): object recognition
- Final competition (7 Dec/17 Dec): search and rescue

Project grading

In-class Demonstration: 50%

Precise evaluation criteria will be defined at the beginning of each phase

Software Quality: 50%

- Choice of abstractions and relations
- Correctness of implementation
- Extendibility and reusability
- Comments and documentation, including "README"

Topics

Control and obstacle avoidance

 ROS and Roboscoop, Modern software engineering tools SCOOP, Robot control and obstacle avoidance, Design patterns

Path planning

Path planning

Object recognition

Robot perception

Search and rescue

Localization, Software architecture in robotics

Lecture schedule

- 1. Introduction to robotics and software engineering
- 2. ROS and Roboscoop
- 3. Control / Modern software engineering tools
- 4. SCOOP
- 5. Obstacle avoidance
- 6. Design patterns

Assignment 1: control and obstacle avoidance

- 7. Path planning
- 8. Robot perception

Assignment 2: path planning

- 9. Localization
- 10. Software architecture for robotics
 Assignment 3: Object recognition
 Assignment 4: Search and rescue

Recommended literature

Software engineering

- Object-Oriented Software Construction, Meyer
- Design Patterns, Gamma, Helm, Johnson, Vlissides
- Pattern-Oriented Software Architecture: Volume 2, Schmidt, Stal, Rohnert, Buschmann

Robotics

- Probabilistic Robotics, Thrun, Burgard, Fox
- Introduction to Autonomous Mobile Robots, by Siegwart, Nourbakhsh, Scaramuzza

Programming language

- > Touch of Class, Meyer
- The C++ Programming Language, Stroustrup

Robots as automata

Robot knight (1495) Leonardo da Vinci

Writer (1774) Pierre Jaquet-Droz

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Robots of the 20th century







Entertainment robot



Exploration robot

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Robots of today



Exploration robot



Surveillance robot



Autonomous vehicle



Entertainment robot





Robotics

Robot: A machine capable of carrying out a complex series of actions automatically, especially one programmable by a computer

Robotics: The branch of technology that deals with the design, construction, operation, and application of robots – Oxford dictionary

Components of robotics

- Perception: vision, touch, range, sound
- Actuation: manipulation, locomotion
- Cognition: navigation, recognition, planning, interaction

Solved challenges

- Navigation in static environment Clausiusstrasse
- Recognition of known objects face, simple objects
- Manipulation of simple, rigid objects <u>beer fetching</u>

Open challenges

- Navigation in dynamic environment Bahnhofstrasse
- Scene understanding a group of people at a party
- Manipulation of complex, deformable objects <u>laundry</u> <u>folding</u>
- Learning over time and knowledge transfer

Robot for the class



What people did last year



Introduction to software engineering

(and software architecture)

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"The application of engineering to software"

Engineering (Wikipedia): "the discipline, art and profession of acquiring and applying technical, scientific, and mathematical knowledge to design and implement materials, structures, machines, devices, systems, and <u>processes</u> that safely realize a desired objective or invention"

A simpler definition of engineering: the application of scientific principles to the construction of artifacts

For this course

The application of engineering principles and techniques, based on mathematics, to the development and operation of possibly large software systems satisfying defined standards of quality Parnas's view

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(Cited in Ghezzi et al.)

"The multi-person construction of multiversion software"

What may be large: any or all of

- Source size (lines of code, LoC)
- Binary size
- Number of users
- Number of developers
- Life of the project (decades...)
- Number of changes, of versions

(Remember Parnas's definition)

Process and product

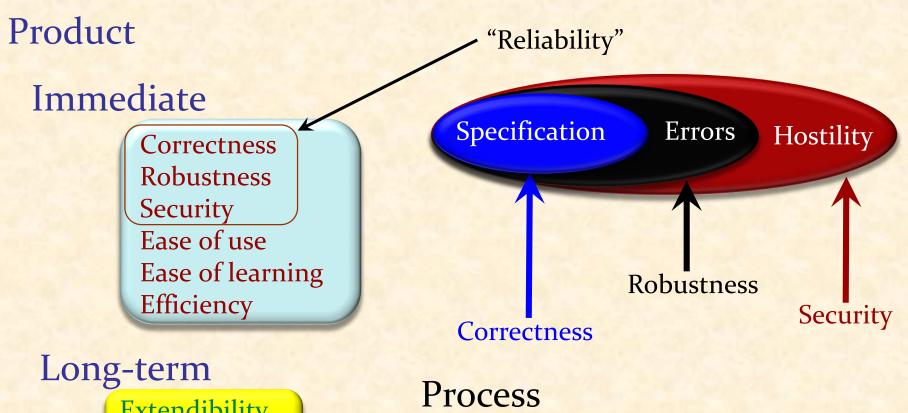
Software engineering affects both:

- Software products
- The processes used to obtain and operate them

Products are not limited to code. Other examples include requirements, design, documentation, test plans, test results, bug reports

Processes exists whether they are formalized or not

Software quality factors



Extendibility Reusability Portability

Timeliness Cost-effectiveness Predictability Reproducibility Self-improvement

Software engineering today

Three cultures:

Process







> Object

The first two are usually seen as exclusive, but all have major contributions to make.

The process culture

Emphasize:

- Plans
- Schedules
- Documents
- Requirements
- > Specifications
- Order of tasks
- Commitments

Examples: Rational Unified Process, CMMI, Waterfall...

CMMI is a catalog of approved practices and goals

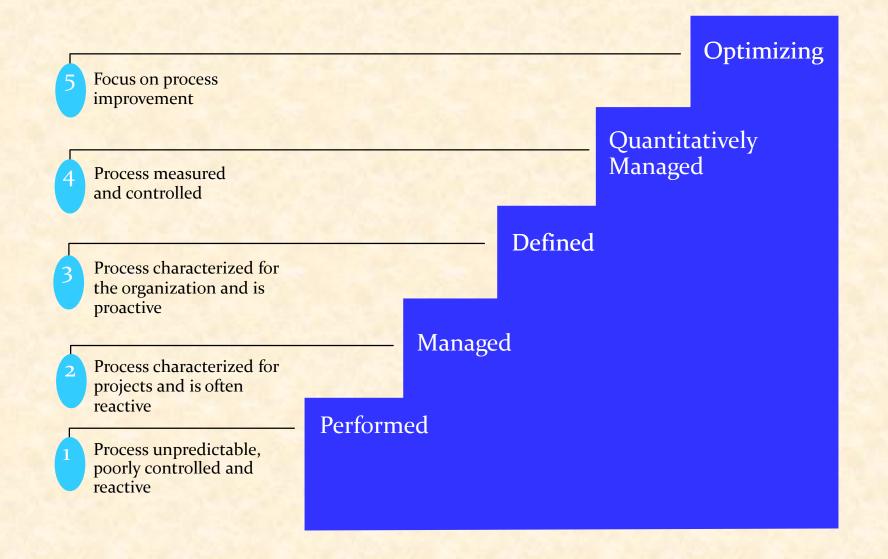
Basic goal: determine the maturity level of the **process** of an organization Focused on process, not technology

Emphasizes **reproducibility** of results (Moving away from "heroic" successes to controlled processes)

Emphasizes **measurement**, based on statistical quality control techniques pioneered by W. Edward Deming & others

Relies on assessment by external team

CMMI maturity levels



Examples: Extreme Programming (XP), Scrum Emphasizes:

- Short iterations
- Emphasis on working code
- Emphasis on testing
- De-emphasis of plans and documents
- > De-emphasis of upfront specifications and design
- > Communication: customer involvement
- > Specific practices, e.g. Pair Programming

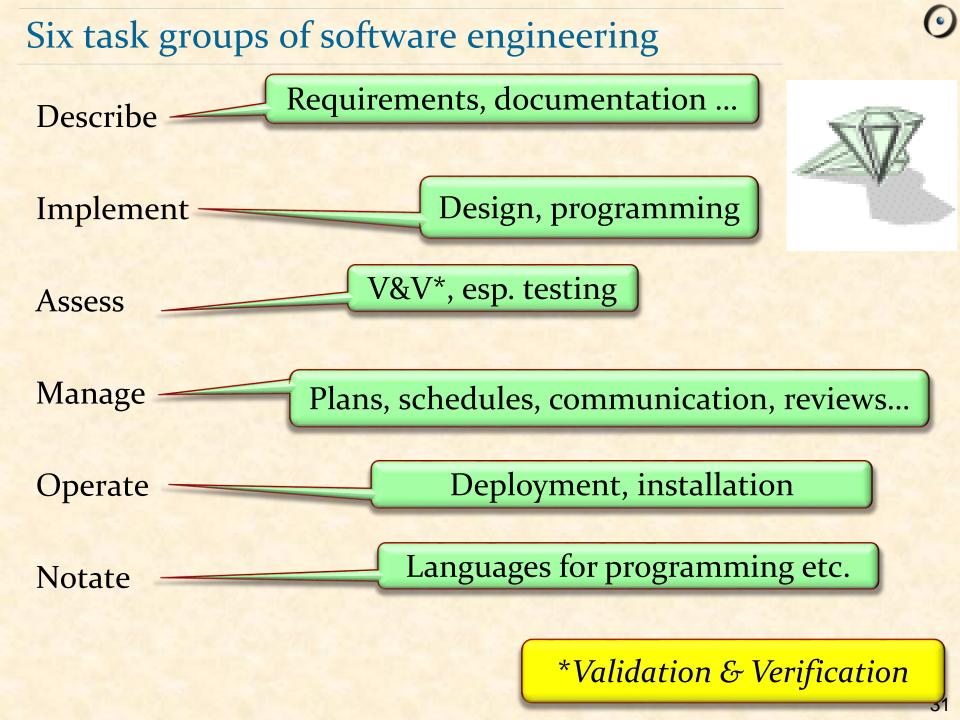
Agile principles

Organizational

- Place the customer at the center
- 2 Develop minimal software:
 - 2.1 Produce minimal functionality
 - 2.2 Produce only the product requested
 - 2.3 Develop only code and tests
- 3 Accept disciplined change
 - 6.1 Do not change requirements during an iteration
- 4 Let the team self-organize
- 5 Maintain a sustainable pace

Technical

- 6 Produce frequent working iterations
- 7 Treat tests as a key resource:
 - 7.1 Do not start any new development until all tests pass
 - 7.2 Test first
- 8 Express requirements through scenarios



Describe an overall distribution of the software construction into tasks, and the ordering of these tasks

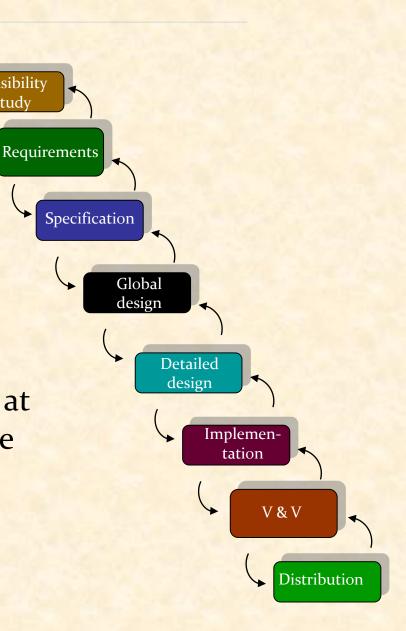
They are models in two ways:

- Provide an abstracted version of reality
- Describe an ideal scheme, not always followed in practice

Lifecycle: the waterfall model

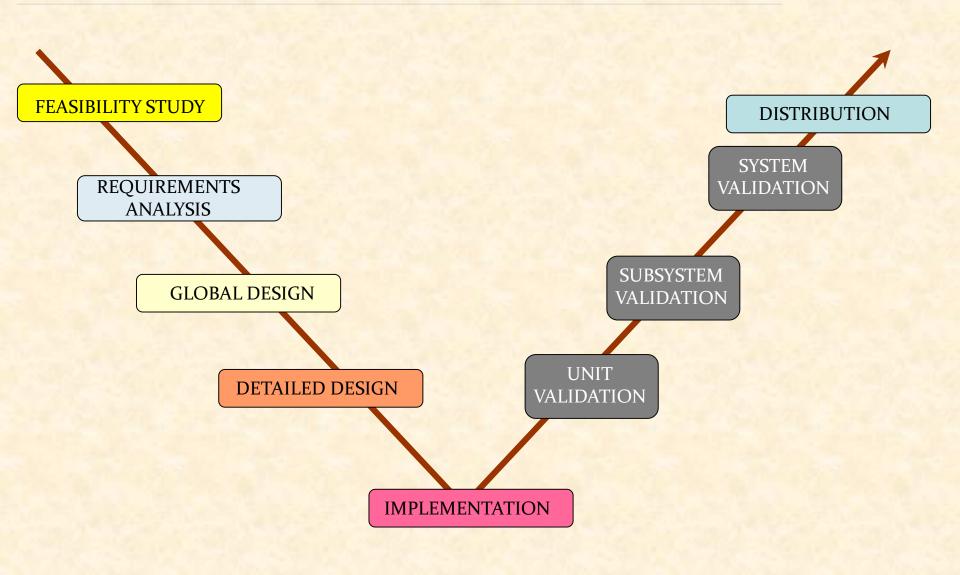
Royce, 1970 (original article actually presented the model to criticize it!)

Succession of steps, with possibility at each step to question and update the results of the preceding step



Feasibility study

A V-shaped variant



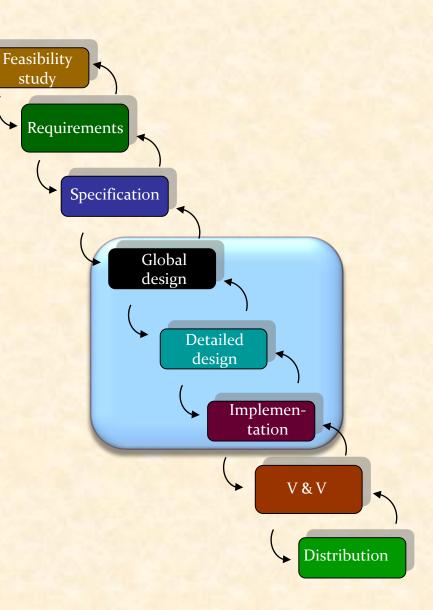
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Arguments for the waterfall

(After B.W. Boehm: Software engineering economics)

- > The activities are necessary
 - (But: merging of middle activities)
- > The order is the right one.

Merging of middle activities



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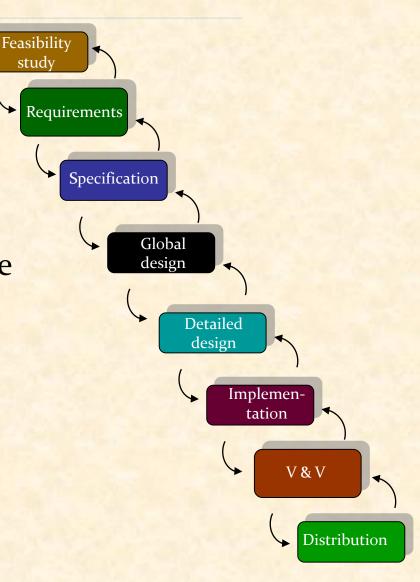
(After B.W. Boehm: Software engineering economics)

- > The activities are necessary
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Problems with the waterfall

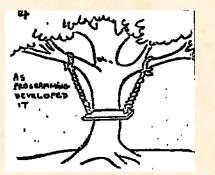
- Late appearance of actual code
- Lack of support for requirements change — and more generally for extendibility and reusability
- Lack of support for the maintenance activity (70% of software costs?)
- Division of labor hampering Total Quality Management
- > Impedance mismatches
- > Highly synchronous model



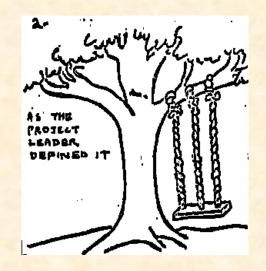
Lifecycle: "impedance mismatches"



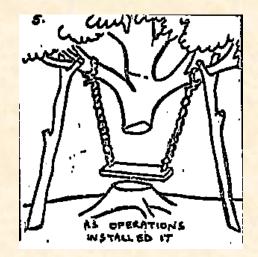
As Management requested it



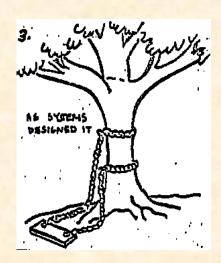
As Programming developed it



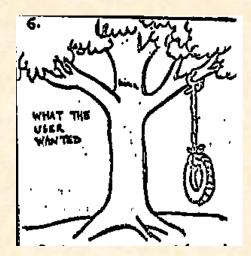
As the Project Leader defined it



As Operations installed it



As Systems designed it



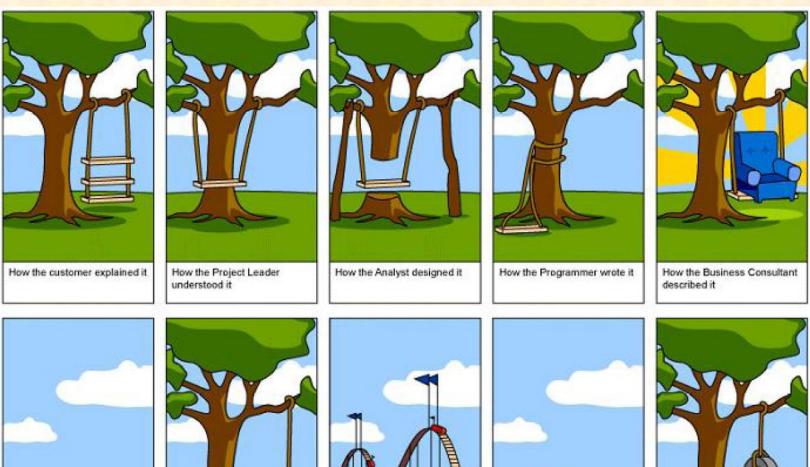
What the user wanted (Pre-1970 cartoon; origin unknown)

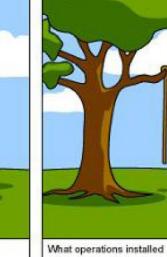
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A modern variant

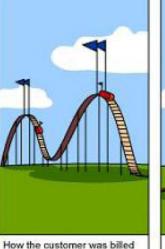
How the project was

documented









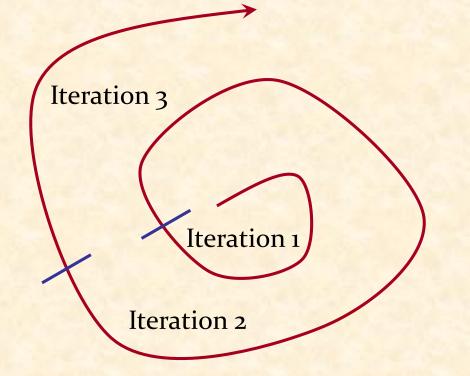
How it was supported



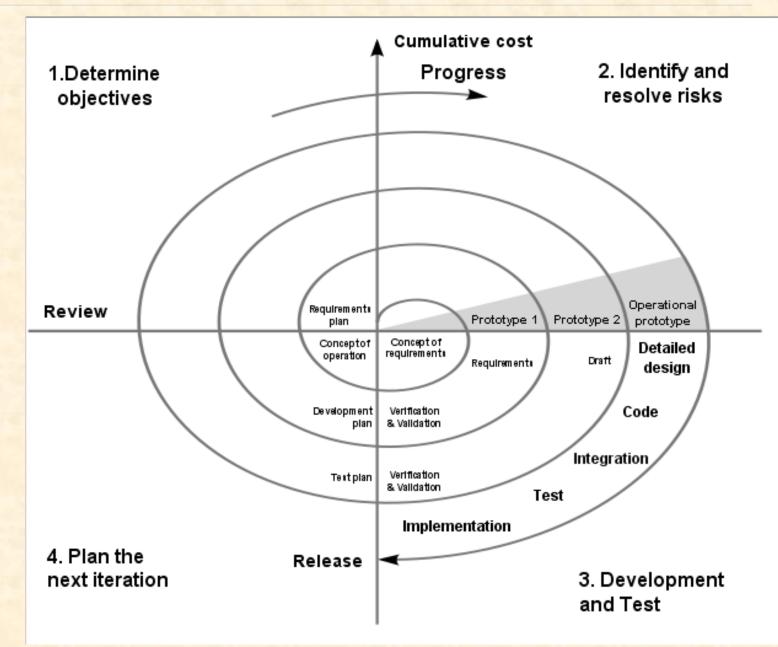
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The spiral model (Boehm)

Apply a waterfall-like approach to successive prototypes



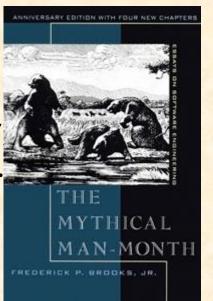
The Spiral model



"Prototyping" in software

The term is used in one of the following meanings:

- > 1. Experimentation:
 - Requirements capture
 - Try specific techniques: GUI, implementation ("buying information")
- 2. Pilot project
- 3. Incremental development
- 4. Throw-away development (Fred Brooks, *The Mythical Man-Month*, 197 "Plan to throw one away, you will anyhow").



The problem with throw-away development

Software development is hard because of the need to reconcile conflicting criteria, e.g. portability and efficiency A prototype typically sacrifices some of these criteria Risk of shipping the prototype

In the 20th-anniversary edition of his book (1995), Brooks admitted that "plan to throw one away" is bad advice

Iterative development

Short iterations ("sprints"), typically 1 month

Every iteration should produce a working system

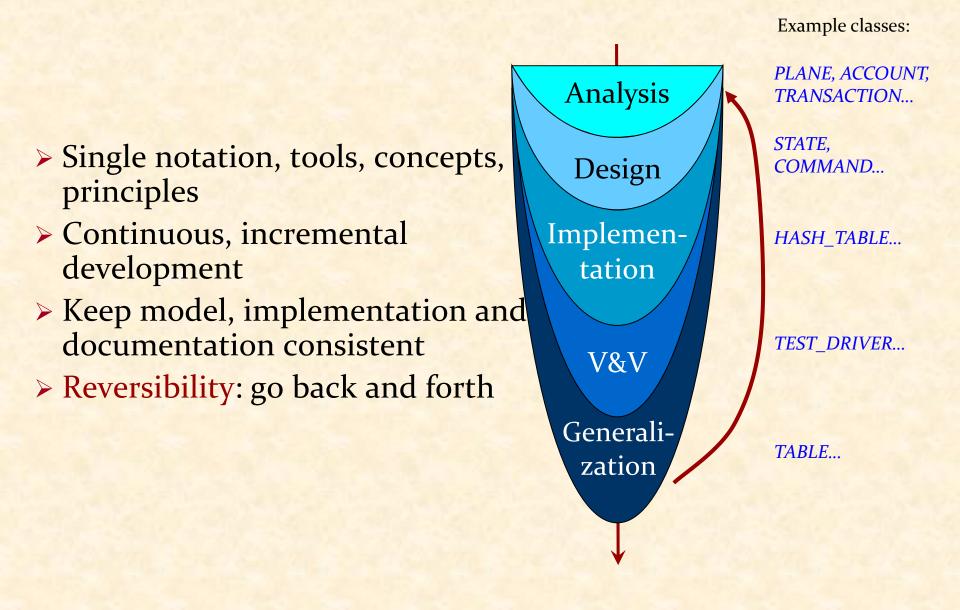
Seamless development:

- Single set of notation, tools, concepts, principles throughout
- Continuous, incremental development
- Keep model, implementation and documentation consistent

Reversibility: can go back and forth

These are in particular some of the ideas behind the Eiffel method

Seamless development



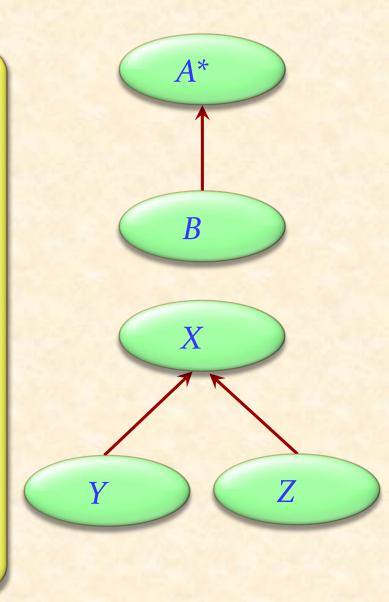
Generalization



Prepare for reuse. For example:

- Remove built-in limits
- Remove dependencies on specifics of project
- Improve documentation, contracts...
- Abstract
- Extract commonalities and revamp inheritance hierarchy

Few companies have the guts to provide the budget for this



Finishing a design

It seems that the sole purpose of the work of engineers, designers, and calculators is to polish and smooth out, lighten this seam, balance that wing until it is no longer noticed, until it is no longer a wing attached to a fuselage, but a form fully unfolded, finally freed from the ore, a sort of mysteriously joined whole, and of the same quality as that of a poem. It seems that perfection is reached, not when there is nothing more to add, but when there is no longer anything to remove.

> (Antoine de Saint-Exupéry, Terre des Hommes, 1937)



Finishing a design

Il semble que tout l'effort industriel de l'homme, tous ses calculs, toutes ses nuits de veille sur



les épures, n'aboutissent [...] qu'à la seule simplicité, comme s'il fallait l'expérience de plusieurs générations pour dégager peu à peu la courbe d'une colonne, d'une carène, ou d'un d'avion, jusqu'à leur rendre la pureté élémentaire de la courbe d'un sein ou d'une épaule. Il semble que le travail des ingénieurs, [...] des calculateurs du bureau d'études ne soit ainsi, en apparence, que de polir et d'effacer, d'alléger [...] Il semble que la perfection soit atteinte non quand il n'y a plus rien à ajouter, mais quand il n'y a plus rien à retrancher.

> (Antoine de Saint-Exupéry, *Terre des Hommes*, 1937)

Steve Jobs, 1998

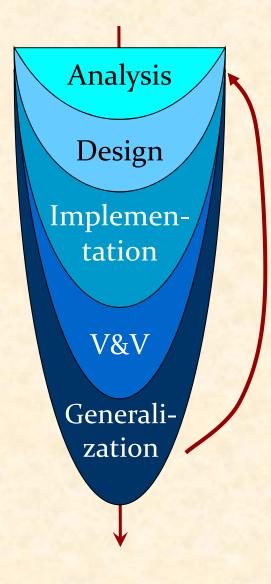
That's been one of my mantras -- focus and simplicity. Simple can be harder than complex: You have to work hard to get your thinking clean to make it simple. But it's worth it in the end because once you get there



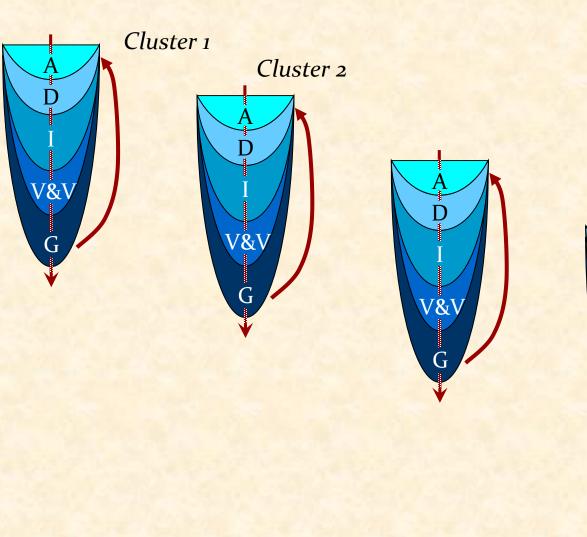
because once you get there, you can move mountains.

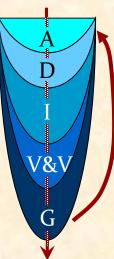
Reversibility





The cluster model





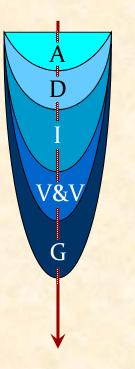
Extremes

"Trickle"



Cluster 1

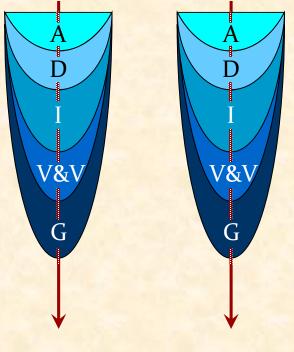
Cluster 2



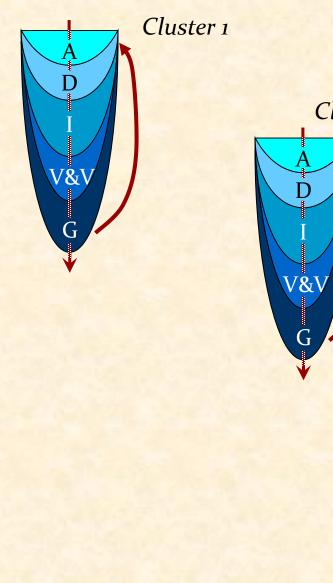
Cluster 1

Cluster 2

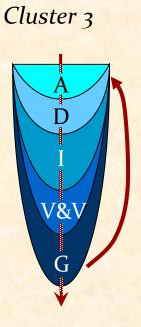
"Clusterfall"



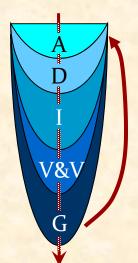
Dynamic rearrangement







Cluster 4



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Bottom-up order of cluster development

Start with most fundamental functionalities, end with user interface

V&V

Specialized

Base technology

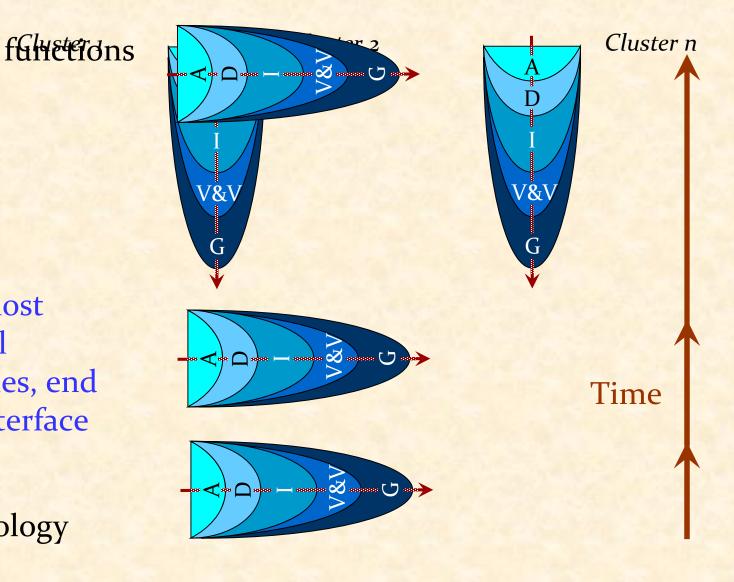


Diagram Tool

- System diagrams can be produced automatically from software text
- Works both ways: update diagrams or update text other view immediately updated
- No need for separate UML tool
- **Metrics** Tool
- **Profiler Tool**

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Documentation generation tool

Complementary approaches

Seamless development: "vertical"

Agile: horizontal

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Software development involves fundamental tasks such as requirements, design, implementation, V&V, maintenance...

Lifecycle models determine how they will be ordered

The Waterfall is still the reference, but many variants are possible, e.g. Spiral, Cluster

Seamless development emphasizes the fundamental unity of the software process