



# Concepts of Concurrent Computation

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Lecture 10: Lock-free approaches

In this lecture you will learn about:

- Problems of the locking-based approach to sharedmemory concurrent programming
- Lock-free programming, a synchronization technique based on atomic read-modify-write primitives
- Linearizability and sequential consistency, two correctness conditions for concurrent objects
- Software transactional memory (STM), a synchronization mechanism based on the idea of database transactions



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# Motivation

## What's wrong with locks? (1)

- It's difficult to program with locks, because it's easy to ...
  - ... forget a lock: danger of data races.
  - ... take too many locks: danger of deadlock.
  - ... take locks in the wrong order: danger of deadlock.
  - ... take the wrong lock: the relation between the lock and the data it protects is not explicit in the program.
- Locks cause blocking:
  - Danger of *priority inversion*: if a lower-priority thread is preempted while holding a lock, higherpriority threads cannot proceed.
  - Danger of *convoying*: other threads queue up waiting while a thread holding a lock is blocked.

- Two concepts related to locks:
  - *lock overhead* (increases with more locks): time for acquiring and releasing locks, and other resources
  - *lock contention* (decreases with more locks): the situation that multiple processes wait for the same lock
- For performance, the developer has to carefully choose the granularity of locking: both lock overhead and contention need to be small.
- Locks are also problematic for designing fault-tolerant systems: If a faulty process halts while holding a lock, no other process can obtain the lock.

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# What's wrong with locks? (3)

 Locks are not composable in general, i.e. they don't support modular programming (building larger programs from smaller blocks).

```
class Account {
    int balance;
    synchronized void deposit(int amount) {
        balance = balance + amount;
    }
    synchronized void withdraw(int amount) {
        balance = balance - amount;
    }
}
```

How to implement the following method?

void transfer(Account acc1, Account acc2, int amount)

# What's wrong with locks? (4)

• Although deposit and withdraw are correctly implemented by themselves, the following is incorrect:

void transfer(Account acc1, Account acc2, int amount) {
 acc1.withdraw(amount);
 acc2.deposit(amount);
}

Instead we would have to add explicit locking code:

```
void transfer(Account acc1, Account acc2, int amount) {
    synchronized (acc1) {
        synchronized (acc2) {
            acc1.withdraw(amount);
            acc2.deposit(amount);
        }
    }
}
```

- Use a pure message-passing approach:
  - Since no data is shared, there is no need for locks
  - Of course message-passing approaches have their own drawbacks, for example
    - potentially larger overhead of messaging
    - the need to copy data which has to be shared
    - potentially slower access to data, e.g. to readonly data structures which need to be shared
- If a shared-memory approach is preferred, the only alternative to using locks is to make the implementation of a concurrent program *lock-free*.

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#### Lock-free approaches

- Lock-free programming using atomic read-modify-write primitives, such as compare and swap (CAS)
- Software transactional memory (STM), a programming model based on the idea of database transactions



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# Lock-free programming

- Lock-free programming is the idea to write sharedmemory concurrent programs that don't use locks but can still ensure thread-safety
- Instead of locks, use stronger atomic operations such as compare-and-swap (atomic read-modify-write primitives)
  - These primitives typically have to be provided by hardware
- Coming up with general lock-free algorithms is hard
- Hence usually one focuses on developing lock-free data structures: stack, list, queue, buffer, ...

#### **Classes of lock-free algorithms**

- For lock-free algorithms one typically distinguishes between the following two classes:
  - *lock-free*: some process completes in a finite number of steps (free from deadlock)
  - wait-free: all processes complete in a finite number of steps (free from starvation)
- Wait-free implies lock-free

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# **Compare-and-swap (recap)**

- Compare-and-swap (CAS) takes three parameters: the address of a memory location, an old and a new value
- The new value is atomically written to the memory location if the content of the location agrees with the old value

```
CAS (x, old, new)
do
if *x = old then
*x := new;
result := true
else
result := false
end
end
```

#### Simple lock-free stack (1)

- Using CAS, we obtain the following lock-free implementation of a stack, due to (Treiber, 1986)
- A stack of elements (here of integer type) is represented as a linked list of nodes
- The top of the stack is denoted by the node *head*

```
class Node {
    Node* next;
    int item;
}
Node* head; // top of the stack
```

## Simple lock-free stack (2)

- In the implementation of push and pop, a common pattern in lock-free algorithms is used:
  - 1. read a value from the current state
  - 2. compute an updated value based on the read value
  - 3. atomically update the state by swapping the new for the old value

```
void push (int value) {
    Node* oldHead;
    Node* newHead := new Node();
    node.item := value;
    do {
        oldHead := head;
        newHead.next := head;
    } while (!CAS(&head, oldHead, newHead));
}
```

## Simple lock-free stack (3)

 If the state changes between steps 1 and 3, the CASoperation fails and the algorithm is repeated until success

```
int pop () {
    Node* oldHead;
    Node* newHead;
    do {
        oldHead := head;
        if(oldHead = null) return EMPTY;
        newHead := oldHead.next;
    } while(!CAS(&head, oldHead, newHead));
    return oldHead.item;
}
```

# The ABA problem (1)

- In the stack example, the following has to be avoided:
  - $T_1$ : starts pop() reads value of current head as X
  - $T_2$ : executes pop(), removing X from the stack
  - $T_2$ : modifies the stack arbitrarily
  - $T_2$ : executes push(X), putting X back on the stack
  - $T_1$ : finishes pop() CAS succeeds, since X is on top

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# The ABA problem (2)

- This problematic pattern is called the *ABA problem*:
  - a value is read from state A
  - the state is changed to state B
  - the CAS operation does not distinguish between A and B, so it assumes it is still A
- The problem is avoided in the simple stack example as push always puts a *new* node, and the old node's memory location is not freed up yet (if the memory address would be reused)

#### More atomic operations

- Besides compare-and-swap there are many atomic operations suggested for lock-free programming
- Not all of the primitives suggested have been implemented in hardware
- The question is which primitives are worth implementing in hardware, i.e. whether these primitives have different strength
- This question has been answered: primitives can be ranked (Herlihy, 1993)

## **Hierarchy of atomic primitives**

• Atomic primitives can then be ranked according to their consensus number (Herlihy, 1993):

Consensus number	Primitive
1	read/write registers
2	test-and-set, fetch-and-add, queue, stack,
:	:
2n - 2	n-register assignment
:	:
∞	memory-to-memory move and swap, compare-and-swap, load- link/store-conditional

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#### **Consensus numbers**

- Each primitive is given a consensus number, the maximum number of processes for which the primitive can implement a consensus protocol (a group of processes agrees on a common value)
- In a system of n or more processes, it is impossible to provide a wait-free implementation of a primitive with consensus number n from a primitive with lower consensus number

# Another primitive: load-link/store-conditional

- load-link/store-conditional is a pair of instructions which together implement a atomic read-modify-write operation
- load-link returns the current value of a memory location
- A subsequent store-conditional to the same location will store a new value only if no updates have occurred to that location since the load-link.
- The store-conditional is guaranteed to fail if updates have occurred, even if the value read by the load-link has since been restored.

## Lock-free programming: Discussion

- Lock-free programming can provide good performance in some situations, avoiding some of the problems mentioned for locks (e.g. priority inversion)
- It's difficult to correctly implement lock-free algorithms (see ABA-problem)
- Most work confined to data structures: for these wellestablished algorithms and implementations are available
- One main restriction is that most read-modify-write primitives operate only on a single word: this leads to unnatural structuring of algorithms

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# Linearizability

## **Sequential objects**

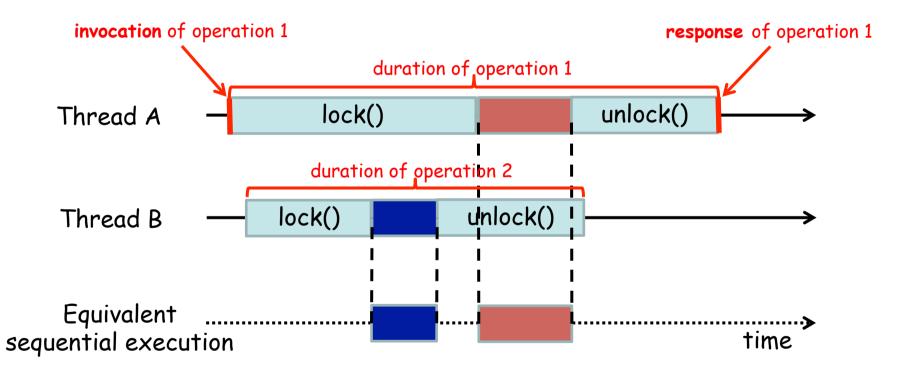
- We can understand a the execution of a system as operations of a collection of (sequential) processes on data objects
- Each object has a type, describing its possible values and the operations for modifying them
- What does it mean for such objects to be correct?
- In a sequential system, where there is only one process, it is easy to specify the behavior of each operation:
  - Pre- and postconditions
  - Intermediate states never visible upon invocation of an operation

#### **Concurrent objects**

- In a concurrent system, operations can potentially be invoked on objects which are in intermediate states
- Hence it is more difficult to define correctness for concurrent objects
- Linearizability provides a correctness condition for concurrent objects

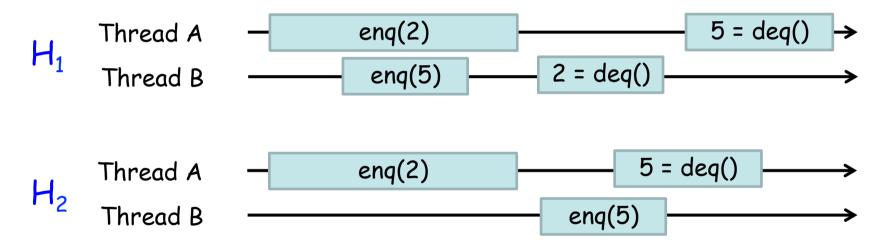
## **Linearizability: Intuition**

 Idea: A concurrent object is linearizable if every concurrent execution of its operations can be shown to be "equivalent" to a sequential execution



# Using the semantics of an object

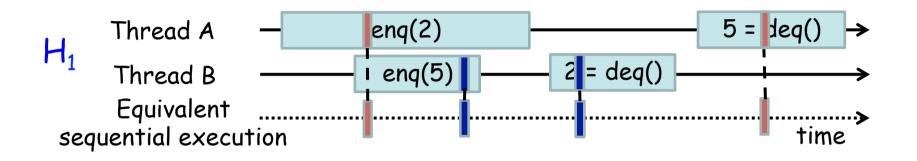
- Imagine an object implementing a FIFO queue with two operations enq(x) and deq().
- To decide whether a concurrent execution is correct, we have to use the object's intended semantics.



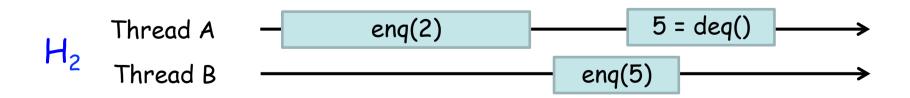
- History  $H_1$  is acceptable, it agrees with the semantics.
- History H<sub>2</sub> is not acceptable: enq(2) was completed before enq(5) started, so 5 couldn't have been dequeued earlier.

### **Observation**

 Observation: Each operation should appear to "take effect" instantaneously at some moment between its invocation and response



• For the second history, no equivalent sequential execution can be found:



- A call of an operation is split into two events:
  - Invocation: [A q.op(a<sub>1</sub>, ..., a<sub>n</sub>)]
  - Response: [A q:Ok(r)]
- Notation:
  - A: thread ID
  - q: object
  - $op(a_1, ..., a_n)$ : invocation of call with arguments
  - Ok(r): successfull response of call with result r
- A *history* is a sequence of invocation and response events
- **Example:** History  $H_1$  can be written as

[A q.enq(2)], [B q.enq(5)], [B q:Ok], [A q:Ok], [A q:Ok], [B q.deq()], [B q:Ok(2)], [A q.deq()], [A q:Ok(5)]

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#### **Projections**

- We can define projections on objects and on threads
- Assume we have a history

 $H = [A q1.enq(2)], [B q2.enq(5)], [B q2:Ok], [A q1:Ok], \\ [B q1.deq()], [B q1:Ok(2)], [A q2.deq()], [A q2:Ok(5)]$ 

- Object projection: H|q1 = [A q1.enq(2)], [A q1:Ok], [B q1.deq()], [B q1:Ok(2)]
- Thread projection: H|A = [A q1.enq(2)], [A q1:Ok], [A q2.deq()], [A q2:Ok(5)]

#### **Sequential histories**

- A response matches an invocation if their object and thread names agree.
- A history is *sequential* if it starts with an invocation and each invocation, except possibly the last, is immediately followed by a matching response

H = [A q.enq(2)], [A q:Ok], [B q.enq(5)], [B q:Ok], ...

 A sequential history is *legal* if it agrees with the sequential specification of each object.

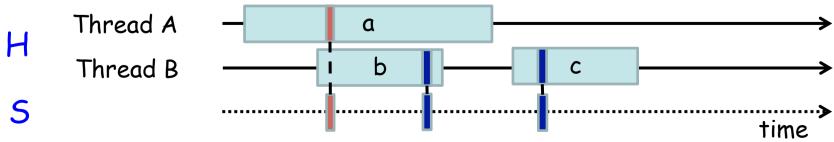
#### **More definitions**

- A call op<sub>1</sub> precedes another call op<sub>2</sub> (op<sub>1</sub> -> op<sub>2</sub>) if op<sub>1</sub>'s response event occurs before op<sub>2</sub>'s invocation event
- We write  $\rightarrow_{H}$  for the precedence relation induced by H
- Example: q.enq(2) -> q.enq(5) in history H
- An invocation is *pending* if it has no matching response
- A history is *complete* if it does not have pending responses
- complete(H) is the subhistory of H with all pending invocations removed

## Linearizability

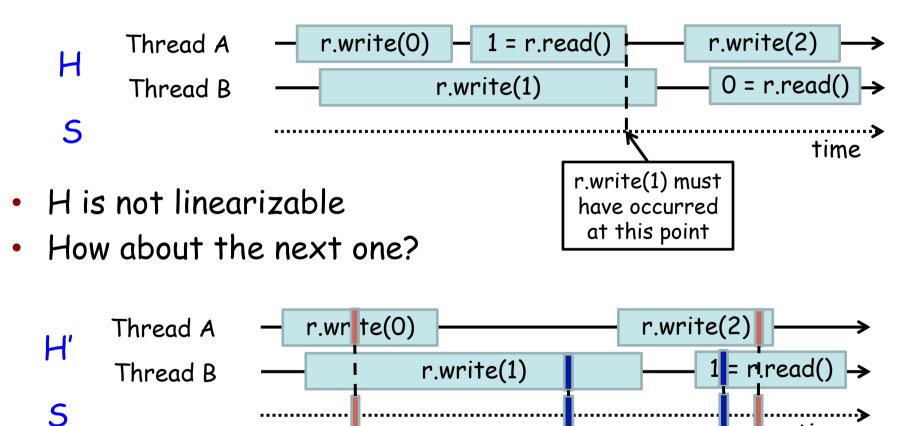
- Two histories H and G are *equivalent* if H|A = G|A for all threads A
- A history H is *linearizable* if it can be extended by appending zero or more response events to a history G such that:
  - complete(G) is equivalent to a legal sequential history S

Example:



## **Example: Linearizability**

• Read/write registers:



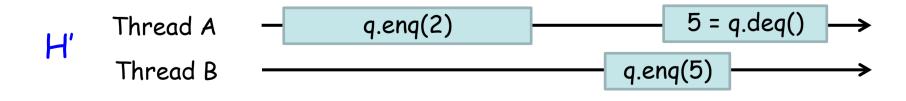
time

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## **Sequential consistency**

- A history H is sequentially consistent if it can be extended by appending zero or more response events to a history G such that:
  - complete(G) is equivalent to a legal sequential history S
- Idea: Calls from a particular thread appear to take place in program order
- H is not sequentially consistent:

• H' is sequentially consistent but not linearizable:



## Compositionality

- Every linearizable history is also sequentially consistent.
- Linearizability is *compositional*: H is linearizable if and only if for each object H|x is linearizable.
- Sequential consistency on the other hand is not compositional.



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# Software Transactional Memory (STM)

#### **Motivation**

- As we have seen, lock-free programming has disadvantages in practice: algorithms can become very complex and have an unnatural structure
- This is because conventional atomic primitives can only operate on one word at a time
- Software transactional memory (STM) aims at simplifying atomic updates of multiple independent words
- STM uses the idea of transaction from database management systems

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#### **Database transactions**

- Database transaction: a sequence of operations performed within a database managament systems, enjoying the ACID properties:
  - Atomicity: Transactions appear to execute completely, or not at all.
  - Consistency: Transactions preserve consistency of the database.
  - Isolation: Other operations cannot access data modified by a currently incomplete transaction.
  - Durability: All committed transactions are guaranteed to persist.
- In the context of STM, we are mostly interested in Atomicity and Isolation.

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# (Hardware) transactional memory

- Software transactional memory is based on earlier ideas of a multiprocessor hardware architecture to support lock-free programming: (hardware) transactional memory (Herlihy and Moss, 1993)
- Not yet implemented, but implementation suggested:
  - adding some specialized cache
  - modifying cache coherence protocols, which maintain consistency between caches and memory and do much of the task already

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#### **Software transactional memory**

- Because of the lag of hardware implementation, development has focused on software implementations of the transaction idea, starting with the work of (Shavit and Touitou, 1995)
- Idea: Allow code to be enclosed by an atomic-block, with the guarantee that it executes atomically with respect to other atomic-blocks
- Currently mostly research prototypes
- The functional language Haskell offers some nice support

## **STM implementations**

- Many implementation variants are possible
- Optimistic implementation approach:
  - atomic-block runs without locking, but writes instead to a transaction log
  - upon completion of the atomic-block, the log is validated and if found consistent the changes are committed
  - if validation fails, the block is reexecuted

- Advantages:
  - Simple and effective programming model
  - Transactions may be composed (Harris et al., 2005)
  - Increased concurrency, no waiting for resources
- Disadvantages:
  - Restrictions on operations within atomic-blocks: since roll-back must be available, no externally observable effects such as IO are allowed
  - Performance loss with respect to fine-grained locking: with current implementations, the overhead of transaction logs and consistency checking amortizes only with larger numbers of processing units