



Concepts of Concurrent Computation

Bertrand Meyer Sebastian Nanz

Lecture 10: An introduction to CSP

Communicating Sequential Processes: C.A.R. Hoare

1978 paper, based in part on ideas of E.W. Dijkstra (guarded commands, 1978 paper and "A Discipline of Programming" book)

Revised with help of S. D. Brooks and A.W. Roscoe

1985 book, revised 2004

Complete reference: *The Theory and Practice of Concurrency*, A. W. Roscoe, Prentice Hall 1997 (2005) (used extensively in the present slides) Concurrency formalism

- > Expresses many concurrent situations elegantly
- Influenced design of several concurrent programming languages, in particular Occam (Transputer)

Calculus

- Formally specified: laws
- > Makes it possible to prove properties of systems

A trace is a sequence of events, for example <coin, coffee, coin, coffee>

Many traces of interest are infinite, for example <coin, coffee, coin, coffee, ...>

(Can be defined formally, e.g by regular expressions, but such traces definition are not part of CSP; they are descriptions of CSP process properties.)

Events come from an *alphabet*. The alphabet of all possible events is written \sum in the following.

A CSP process is characterized (although not necessarily defined fully) by the set of its traces. For example a process may have the trace set

```
{<>,
<coin, coffee>,
<coin, tea>}
```

The special process STOP has a trace set consisting of a single, empty trace:

Basic CSP syntax

P ::=

- $a \rightarrow Q$ | -- Engages in a, then acts like Q
- Q ∏ R | -- Internal choice
- Q □ R | -- External choice
- Q | R | -- Concurrency (E: subset of alphabet)
- $Q \parallel R \parallel --$ Lock-step concurrency (same as $Q \parallel R$)
- $Q \setminus E$ | -- Hiding
- $\mu Q \bullet f(Q)$ -- Recursion

Basic: $a \rightarrow P$ Generalization: $x: E \rightarrow P(x)$

Accepts any event from E, then executes P(x) where x is that event

Also written ? $x: E \rightarrow P(x)$

Note that if E is empty then $x: E \rightarrow P(x)$ is STOP for any P

- 1. P || Q = Q || P
- 2. (P || (Q || R)) = ((P || Q) || R)
- 3. P || STOP = STOP
- 4. $(c \rightarrow P) || (c \rightarrow Q) = (c \rightarrow (P || Q))$
- 5. $(c \rightarrow P) \mid | (d \rightarrow Q) = STOP$ -- If $c \neq d$
- 6. $(x: A \to P(x)) || (y: B \to Q(y)) =$ $(z: (A \cap B) \to (P(z) || Q(z))$

Processes engage in events Example of basic notation: CVM = (coin → coffee → coin → coffee → STOP)

Right associativity: the above is an abbreviation for $CVM = (coin \rightarrow (coffee \rightarrow (coin \rightarrow (coffee \rightarrow STOP))))$

Trace set of CVM: {<coin, coffee, coin, coffee>}

The events of a process are taken from its alphabet: $\alpha(CVM) = \{coin, coffee\}$

STOP can engage in no events

traces ($e \rightarrow P$) = {<e> + s | s \in traces (P)}

P :::=

- $a \rightarrow Q$ | -- Engages in a, then acts like Q
- Q ∏ R | -- Internal choice
- Q□R | -- External choice
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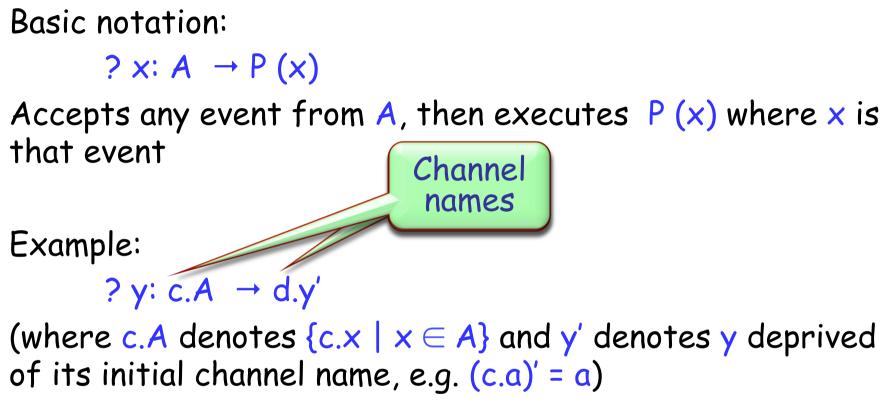
Recursion

 $CLOCK = (tick \rightarrow CLOCK)$

This is an abbreviation for $CLOCK = \mu P \bullet (tick \rightarrow P)$

A recursive definition is a fixpoint equation. The μ notation denotes the fixpoint

Accepting one of a set of events; channels



More convenient notation for such cases involving channels:

c? x: $A \rightarrow d!x$

()

A simple buffer

 $COPY = c? x: A \rightarrow d!x \rightarrow COPY$

lacksquare

```
COPYBIT = (in.0 \rightarrow out.0 \rightarrow COPYBIT
\Box
in.1 \rightarrow out.1 \rightarrow COPYBIT)
```

 $COPY1 = in? x: A \rightarrow out1!x \rightarrow COPY1$

 $COPY2 = in? x: B \rightarrow out2!x \rightarrow COPY2$

 $COPY3 = COPY1 \square COPY2$

Consider

```
CHM1 = (in1f \rightarrow out50rp \rightarrow out20rp \rightarrow out20rp \rightarrow out10rp)CHM2 = (in1f \rightarrow out50rp \rightarrow out50rp)
```

```
CHM = CHM1 \square CHM2
```

Consider P = $?x: A \rightarrow P'$	
$Q = ?x: B \to Q'$	
Then P Q = ? x →	
≻ (P' Q')	$if x \in A \cap B$
> STOP	otherwise

(to be generalized soon)

 \odot

```
VMC =
          (in2f \rightarrow
                    ((large \rightarrow VMC) \Box
                    (small \rightarrow out1f \rightarrow VMC))
          (in1f \rightarrow
                    ((small \rightarrow VMC) \Box
                    (in1f \rightarrow large \rightarrow VMC))
FOOLCUST = (in2f \rightarrow large \rightarrow FOOLCUST \square
                               in 1f \rightarrow large \rightarrow FOOLCUST)
FV = FOOLCUST || VMC =
                    \mu P \bullet (in2f \rightarrow large \rightarrow P \Box in1f \rightarrow STOP)
```

Consider

 $P = a \rightarrow b \rightarrow Q$

Assuming \mathbf{Q} does not involve **b**, then

 $P \setminus \{b\} = a \rightarrow Q$

```
More generally:

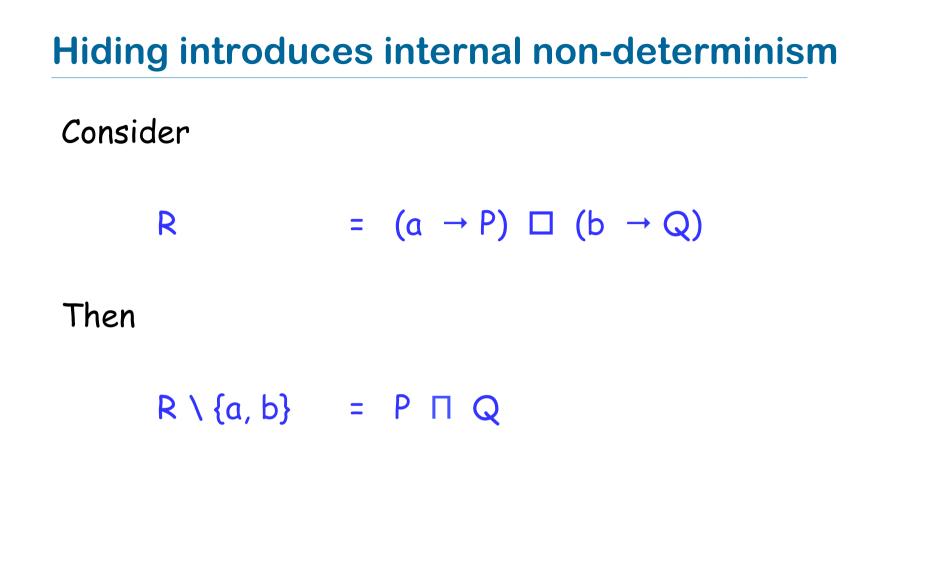
(a \rightarrow P) \setminus E =

P \setminus E if a \in E

a \rightarrow (P \setminus E) if a \notin E
```

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 \odot



Internal non-deterministic choice

```
\begin{array}{l} C\text{H1F} = (\text{in1f} \rightarrow \\ & ((\text{out2Orp} \rightarrow \text{out2Orp} \rightarrow \\ & \text{out2Orp} \rightarrow \text{out2Orp} \rightarrow \text{out2Orp} \rightarrow \text{CH1F}) \\ & \Pi \\ & (\text{out5Orp} \rightarrow \text{out5Orp} \rightarrow \text{CH1F}))) \end{array}
```

Non-deterministic internal choice: another application

TRANSMIT (x) = in?x \rightarrow LOSSY (x) LOSSY (x) = out!x \rightarrow TRANSMIT (x) \square out!x \rightarrow LOSSY (x) \square TRANSMIT (x)

The general concurrency operator

Consider $P = ?x: A \rightarrow P'$ $Q = ?x: B \rightarrow Q'$	
Then	
Then $P \mid Q = ? \times \rightarrow P' \mid Q' = P' \mid Q'$	$if x \in E \cap A \cap B$
▷ P' Q	if $x \in A-B-E$
► P Q'	if $x \in B-A-E$
> (P' Q) Π (P Q') E	if $x \in (A \cap B) - E$

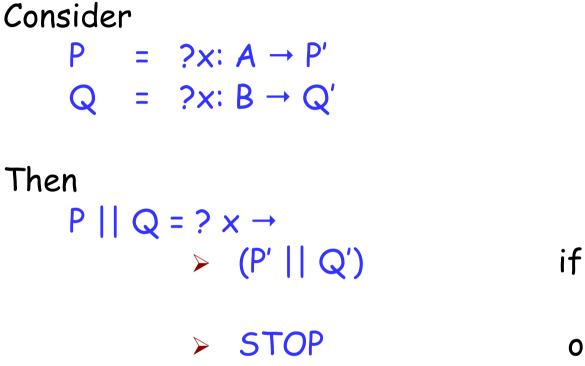
Lock-step concurrency:

P || Q = P || Q

Interleaving:

 $P ||| Q = P ||_{\emptyset} Q$

Lock-step concurrency (reminder)



if $x \in E \cap A \cap B$

otherwise

Laws of non-deterministic internal choice

```
P \sqcap P = P
P \sqcap Q = Q \sqcap P
P \sqcap (Q \sqcap R) = (P \sqcap Q) \sqcap R
x \rightarrow (P \sqcap Q) = (x \rightarrow P) \sqcap (x \rightarrow Q)
```

 $P || (Q \Pi R) = (P || Q) \Pi (P || R)$ $(P \Pi Q) || R = (P || R) \Pi (Q || R)$

The recursion operator is not distributive; consider:

 $P = \mu X \bullet ((a \rightarrow X) \sqcap (b \rightarrow X))$ $Q = (\mu X \bullet (a \rightarrow X)) \sqcap (\mu X \bullet (b \rightarrow X))$

From previous slide: $x \rightarrow (P \sqcap Q) = (x \rightarrow P) \sqcap (x \rightarrow Q)$

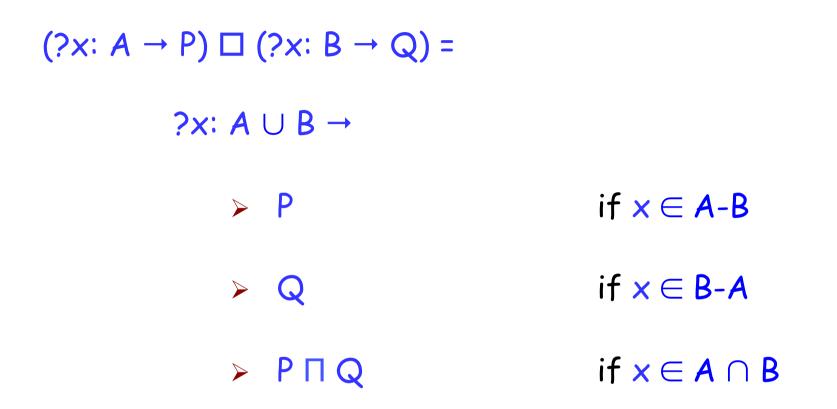
The question was asked in class of whether a similar property also applies to external choice \square

```
The conjectured property is

x \rightarrow (P \Box Q) = (x \rightarrow P) \Box (x \rightarrow Q)
```

It does not hold, since $(x \rightarrow P) \square (x \rightarrow Q) = x \rightarrow (P \sqcap Q)$ (As a consequence of rule on next page)

General property of external choice



traces ($e \rightarrow P$) = {<e> + s | s \in traces (P)}

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- $Q \setminus E$ | -- Hiding
- $\mu Q \bullet f(Q)$ -- Recursion

Process Q refines (specifically, trace-refines) process P if

traces (Q) \subseteq traces (P)

For example:

P refines $P \sqcap Q$

The trace model is not enough

The traces of and are the same: traces (P \square Q) = traces (P) \cup traces (Q) traces (P \square Q) = traces (P) \cup traces (Q)

But the processes can behave differently if for example:

P = $a \rightarrow b \rightarrow STOP$ Q = $b \rightarrow a \rightarrow STOP$

Traces define what a process may do, not what it may refuse to do

For a process P and a trace t of P:

- ➤ An event set es ∈ P (∑) is a refusal set if P can forever refuse all events in es
- > Refusals (P) is the set of P's refusal sets
- > Convention: keep only maximal refusal sets (if X is a refusal set and $Y \subseteq X$, then Y is a refusal set)

This also leads to a notion of "failure":

Failures (P, t) is Refusals (P / t)

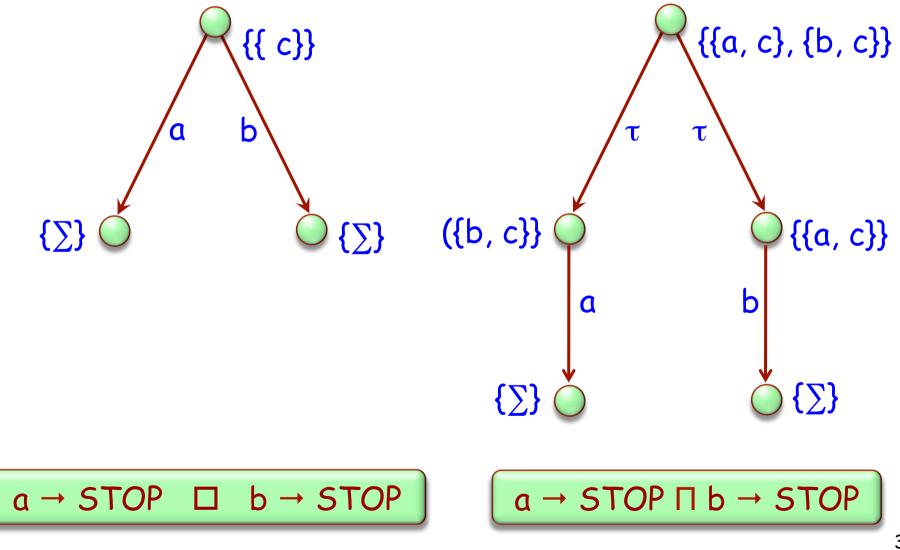
where P/t is P after t: traces (P / t) = {u | t + u \in traces (P)) Compare $P = a \rightarrow STOP \square b \rightarrow STOP$ $Q = a \rightarrow STOP \sqcap b \rightarrow STOP$

Same traces, but:

- ➤ Refusals (P) = Ø
- > Refusals (Q) = {{a}, {b}}

Refusal sets (from labeled transition diagram)

∑ = { a, b, c}



 \odot

A more complete notion of refinement

Process Q failures-refines process P if both

traces (Q) \subseteq traces (P) failures (Q) \subseteq failures (P)

Makes it possible to distinguish between \Box and \Box

A process diverges if it is not refusing all events but not communicating with the environment

This happens if a process can engage in an infinite sequence of $\boldsymbol{\tau}$ transitions

An example of diverging process:

 $(\mu p.a \rightarrow p) \land a$

The divergence model (Brookes, Roscoe)

CSP semantics is often expressed through a failures set A failure is of the form

[s, X]

where ${\bf s}$ is a trace (sequence of events) and ${\bf X}$ a finite set of events

A failure set must satisfy the following properties:

- ▶ [<>, Ø] ∈ F
- > [s+t,∅]∈F ⇒ [s,∅]∈F
- \succ [s, X] ∈ F \land Y ⊆ X \Rightarrow [s, Y] ∈ F
- > [s, X] ∈ F ∧ [s + <c>, Ø] ∉ F ⇒ [s, X ∪ {c}] ∈ F

Basic CSP syntax

P ::=

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CSP laws in the divergence model (1/2)

```
P \square P \equiv_M P
                     P \square Q \equiv_{\mathcal{M}} Q \square P
           P \square (Q \square R) \equiv_M (P \square Q) \square R
           P \square (Q \sqcap R) \equiv_M (P \square Q) \sqcap (P \square R)
           P \sqcap (Q \square R) \equiv_M (P \sqcap Q) \square (P \sqcap R)
             P \square \text{STOP} \equiv_M P
       (a \to (P \sqcap Q)) \equiv_M (a \to P) \sqcap (a \to Q)
(a \to P) \square (a \to Q) \equiv_M (a \to P) \sqcap (a \to Q)
                     P \sqcap P \equiv M P
                     P \sqcap Q \equiv_M Q \sqcap P
           P \sqcap (Q \sqcap R) \equiv_M (P \sqcap Q) \sqcap R
                     P \parallel Q \equiv_M Q \parallel P
            P \parallel (Q \parallel R) \equiv_{M} (P \parallel Q) \parallel R
           P \parallel (Q \sqcap R) \equiv_M (P \parallel Q) \sqcap (P \parallel R)
(a \to P) \parallel (b \to Q) \equiv_M \text{STOP} if a \neq b
                                 \equiv_M (a \to (P \parallel Q)) \text{ if } a = b
              P \parallel \text{STOP} \equiv_M \text{STOP}
```

(From: Brooks & Roscoe 85)

CSP laws (2/2)

```
P|||Q \equiv_M Q|||P
          (P|||Q)|||R \equiv_M P|||(Q|||R)
          P|||(Q \sqcap R) \equiv_{\mathcal{M}} (P|||Q) \sqcap (P|||R)
(a \to P) \parallel \mid (b \to Q) \equiv_M (a \to (P \parallel \mid (b \to Q))) \square (b \to ((a \to P) \parallel \mid Q))
             P;(Q;R) \equiv_M (P;Q);R
            \text{STOP} ||| Q \equiv_M Q
               SKIP: Q \equiv_M Q
              STOP; Q \equiv_M STOP
            P; (Q \sqcap R) \equiv_M (P; Q) \sqcap (P; R)
            (P \sqcap Q); R \equiv_M (P; R) \sqcap (Q; R)
           (a \to P); Q \equiv_M (a \to P; Q) if a \neq \checkmark
                (P \setminus a) \setminus b \equiv_M (P \setminus b) \setminus a
                (P \setminus a) \setminus a \equiv_M P \setminus a
            (a \to P) \setminus b \equiv_M (a \to P \setminus b) if a \neq b
                              \equiv_M P \setminus b if a = b
             (P \sqcap Q) \setminus a \equiv_{\mathcal{M}} (P \setminus a) \sqcap (Q \setminus a)
```

Non-timed:

- > The \checkmark event (not in Σ): successful termination
- Skip : successfully terminates
- Sequential composition: P ; Q
- \succ \perp : diverging process

Timed:

P / Q: interrupt

- $> P \stackrel{t}{>} Q$: timeout
- > $a \xrightarrow{!} P$: communicate immediately
- > WAIT t: same as STOP $\stackrel{t}{\triangleright}$ SKIP

V1 = coin.in → ((coke → V1) □ (fanta → V1)) $\stackrel{60}{\triangleright}$ (coin.out $\stackrel{!}{\rightarrow}$ V1)

Some laws no longer hold

```
P || STOP = STOP if P \neq \perp
 \perp || STOP = \perp
```

```
(a \rightarrow P) \setminus b = a \rightarrow (P \setminus b) if a \neq b
(a \rightarrow P) \setminus a = P \setminus a
```

A calculus based on mathematical laws

Provides a general model of computation based on communication

Serves both as specification of concurrent systems and as a guide to implementation

One of the most influential models for concurrency work

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1978 paper, based in part on ideas of E.W. Dijkstra (guarded commands, 1978 paper and "A Discipline of Programming" book)

Revised with help of S. D. Brooks and A.W. Roscoe

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- > Expresses many concurrent situations elegantly
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Many traces of interest are infinite, for example <coin, coffee, coin, coffee, ...>

(Can be defined formally, e.g by regular expressions, but such traces definition are not part of CSP; they are descriptions of CSP process properties.)

Events come from an *alphabet*. The alphabet of all possible events is written \sum in the following.

A CSP process is characterized (although not necessarily defined fully) by the set of its traces. For example a process may have the trace set

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The special process STOP has a trace set consisting of a single, empty trace:

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- $Q \setminus E$ | -- Hiding
- $\mu Q \bullet f(Q)$ -- Recursion

Basic: $a \rightarrow P$ Generalization: $x: E \rightarrow P(x)$

Accepts any event from E, then executes P(x) where x is that event

Also written ? x: $E \rightarrow P(x)$

Note that if E is empty then $x: E \rightarrow P(x)$ is STOP for any P

- 1. P || Q = Q || P
- 2. (P || (Q || R)) = ((P || Q) || R)
- 3. P || STOP = STOP
- 4. $(c \rightarrow P) || (c \rightarrow Q) = (c \rightarrow (P || Q))$
- 5. $(c \rightarrow P) \mid | (d \rightarrow Q) = STOP$ -- If $c \neq d$
- 6. $(x: A \to P(x)) || (y: B \to Q(y)) =$ $(z: (A \cap B) \to (P(z) || Q(z))$

Processes engage in events Example of basic notation: CVM = (coin → coffee → coin → coffee → STOP)

Right associativity: the above is an abbreviation for $CVM = (coin \rightarrow (coffee \rightarrow (coin \rightarrow (coffee \rightarrow STOP))))$

Trace set of CVM: {<coin, coffee, coin, coffee>}

The events of a process are taken from its alphabet: $\alpha(CVM) = \{coin, coffee\}$

STOP can engage in no events

traces ($e \rightarrow P$) = {<e> + s | s \in traces (P)}

P :::=

- $a \rightarrow Q$ | -- Engages in a, then acts like Q
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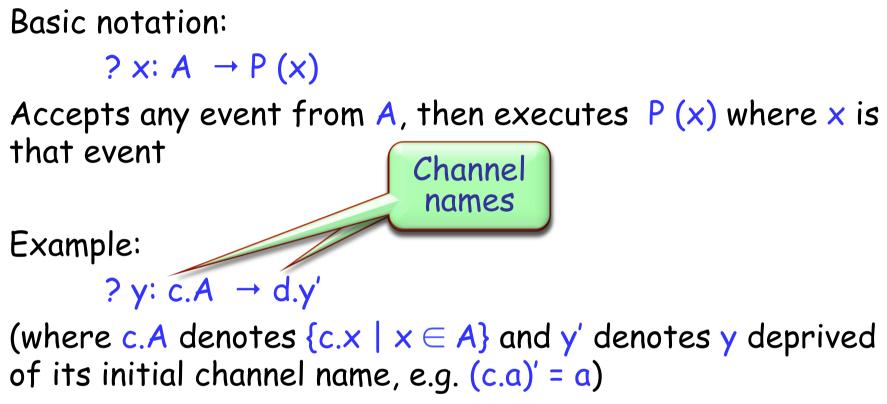
Recursion

 $CLOCK = (tick \rightarrow CLOCK)$

This is an abbreviation for $CLOCK = \mu P \bullet (tick \rightarrow P)$

A recursive definition is a fixpoint equation. The μ notation denotes the fixpoint

Accepting one of a set of events; channels



More convenient notation for such cases involving channels:

c? x: $A \rightarrow d!x$

()

A simple buffer

 $COPY = c? x: A \rightarrow d!x \rightarrow COPY$

 \odot

```
COPYBIT = (in.0 \rightarrow out.0 \rightarrow COPYBIT
\Box
in.1 \rightarrow out.1 \rightarrow COPYBIT)
```

 $COPY1 = in? x: A \rightarrow out1!x \rightarrow COPY1$

 $COPY2 = in? x: B \rightarrow out2!x \rightarrow COPY2$

 $COPY3 = COPY1 \square COPY2$

Consider

```
CHM1 = (in1f \rightarrow out50rp \rightarrow out20rp \rightarrow out20rp \rightarrow out10rp)CHM2 = (in1f \rightarrow out50rp \rightarrow out50rp)
```

```
CHM = CHM1 \square CHM2
```

Consider $P = ?x: A \rightarrow P'$ $Q = ?x: B \rightarrow Q'$

Then

 $P \mid \mid Q = ? x: A \cap B \rightarrow (P' \mid \mid Q')$

Note that P || Q is STOP for any event $x \notin A \cap B$

(to be generalized soon)

```
VMC =
          (in2f \rightarrow
                    ((large \rightarrow VMC) \Box
                    (small \rightarrow out1f \rightarrow VMC))
          (in1f \rightarrow
                    ((small \rightarrow VMC) \square
                    (in1f \rightarrow large \rightarrow VMC))
FOOLCUST = (in2f \rightarrow large \rightarrow FOOLCUST \square
                               in 1f \rightarrow large \rightarrow FOOLCUST)
FV = FOOLCUST || VMC =
                    \mu P \bullet (in2f \rightarrow large \rightarrow FV \Box in1f \rightarrow STOP)
```

Consider

 $P = a \rightarrow b \rightarrow Q$

Assuming \mathbf{Q} does not involve **b**, then

 $P \setminus \{b\} = a \rightarrow Q$

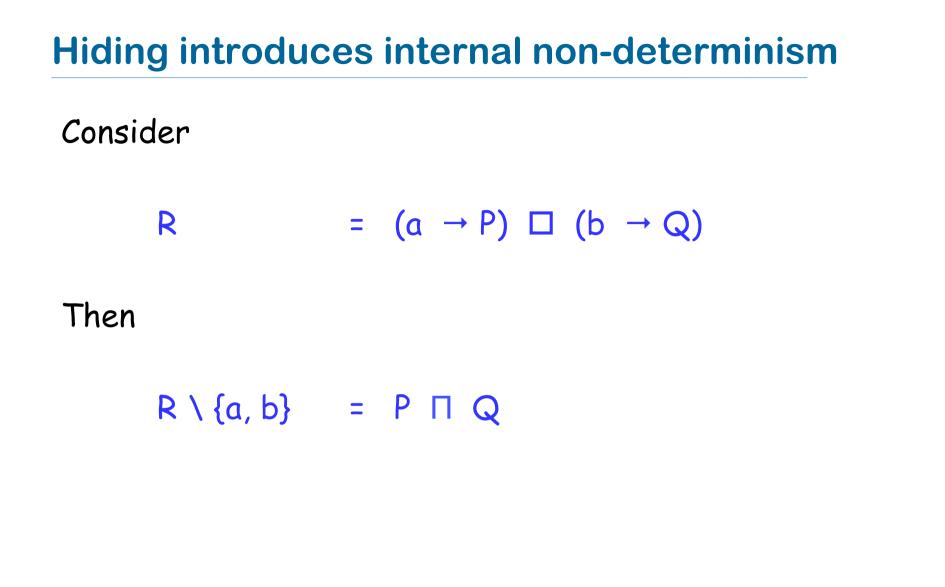
```
More generally:

(a \rightarrow P) \setminus E =

P \setminus E if a \in E

a \rightarrow (P \setminus E) if a \notin E
```

 \odot



Internal non-deterministic choice

```
\begin{array}{l} C\text{H1F} = (\text{in1f} \rightarrow \\ & ((\text{out2Orp} \rightarrow \text{out2Orp} \rightarrow \\ & \text{out2Orp} \rightarrow \text{out2Orp} \rightarrow \text{out2Orp} \rightarrow \text{CH1F}) \\ & \Pi \\ & (\text{out5Orp} \rightarrow \text{out5Orp} \rightarrow \text{CH1F}))) \end{array}
```

Non-deterministic internal choice: another application

TRANSMIT (x) = in?x \rightarrow LOSSY (x) LOSSY (x) = out!x \rightarrow TRANSMIT (x) \square out!x \rightarrow LOSSY (x) \square TRANSMIT (x)

The general concurrency operator

Consider $P = ?x: A \rightarrow P'$ $Q = ?x: B \rightarrow Q'$	
Then	
$P \prod_{i \in Q} Q = ? X \rightarrow P \prod_{i \in Q} Q = P \prod_{i$	
Then $P \mid Q = ? \times \rightarrow \\ E \qquad > P' \mid Q' \\ E \qquad \qquad$	$if x \in E \cap A \cap B$
P' ↓ Q E	if $x \in A-B-E$
► P Q' E	if $x \in B-A-E$
> (P' Q) Π (P Q') E E	if x ∈ (A ∩ B) - E

Lock-step concurrency:

P || Q = P || Q

Interleaving:

 $P ||| Q = P ||_{\emptyset} Q$

Consider $P = ?x: A \rightarrow P'$ $Q = ?x: B \rightarrow Q'$

Then

 $\mathsf{P} \mid \mid \mathsf{Q} = ? : \mathsf{A} \cap \mathsf{B} \to (\mathsf{P}' \mid \mid \mathsf{Q}')$

Note that P || Q is STOP for any event $x \notin A \cap B$

(to be generalized soon)

Laws of non-deterministic internal choice

```
P \sqcap P = P
P \sqcap Q = Q \sqcap P
P \sqcap (Q \sqcap R) = (P \sqcap Q) \sqcap R
x \rightarrow (P \sqcap Q) = (x \rightarrow P) \sqcap (x \rightarrow Q)
```

 $P || (Q \Pi R) = (P || Q) \Pi (P || R)$ $(P \Pi Q) || R = (P || R) \Pi (Q || R)$

The recursion operator is not distributive; consider:

 $P = \mu X \bullet ((a \rightarrow X) \sqcap (b \rightarrow X))$ $Q = (\mu X \bullet (a \rightarrow X)) \sqcap (\mu X \bullet (b \rightarrow X))$

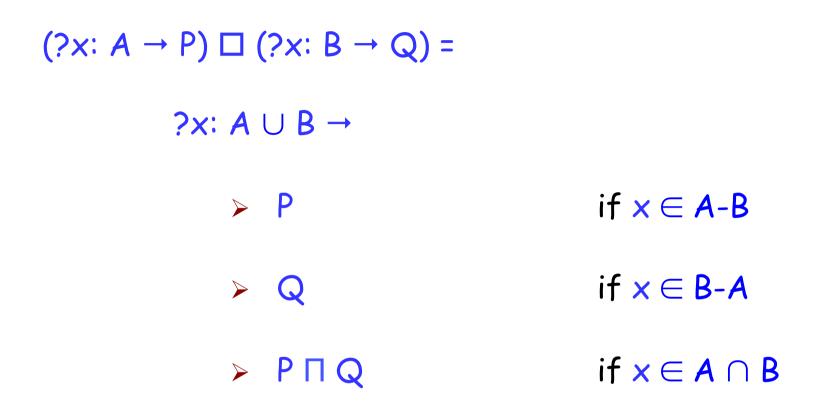
From previous slide: $x \rightarrow (P \sqcap Q) = (x \rightarrow P) \sqcap (x \rightarrow Q)$

The question was asked in class of whether a similar property also applies to external choice \Box

```
The conjectured property is x \rightarrow (P \Box Q) = (x \rightarrow P) \Box (x \rightarrow Q)
```

It does not hold, since $(x \rightarrow P) \square (x \rightarrow Q) = x \rightarrow (P \sqcap Q)$ (As a consequence of rule on next page)

General property of external choice



traces ($e \rightarrow P$) = {<e> + s | s \in traces (P)}

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Process Q refines (specifically, trace-refines) process P if

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For example:

P refines $P \sqcap Q$

The trace model is not enough

The traces of and are the same: traces (P \square Q) = traces (P) \cup traces (Q) traces (P \sqcap Q) = traces (P) \cup traces (Q)

But the processes can behave differently if for example:

P = $a \rightarrow b \rightarrow STOP$ Q = $b \rightarrow a \rightarrow STOP$

Traces define what a process may do, not what it may refuse to do

For a process P and a trace t of P:

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This also leads to a notion of "failure":

Failures (P, t) is Refusals (P / t)

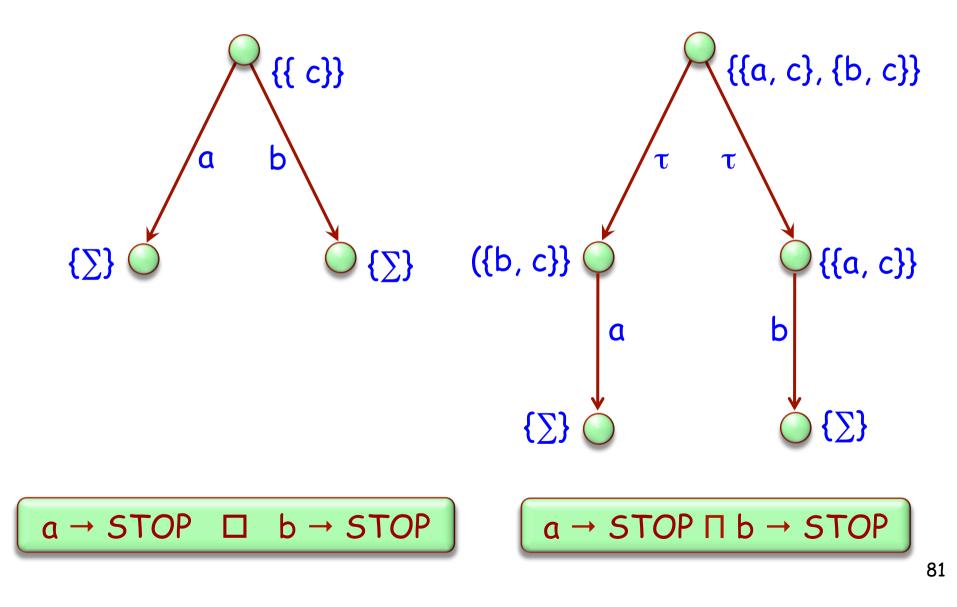
where P/t is P after t: traces (P / t) = {u | t + u \in traces (P)) Compare $P = a \rightarrow STOP \square b \rightarrow STOP$ $Q = a \rightarrow STOP \sqcap b \rightarrow STOP$

Same traces, but:

- ➤ Refusals (P) = Ø
- Refusals (Q) = {{a}, {b}}

Refusal sets (from labeled transition diagram)

∑ = { a, b, c}



A more complete notion of refinement

Process Q failures-refines process P if both

traces (Q) \subseteq traces (P) failures (Q) \subseteq failures (P)

Makes it possible to distinguish between \Box and \Box

A process diverges if it is not refusing all events but not communicating with the environment

This happens if a process can engage in an infinite sequence of $\boldsymbol{\tau}$ transitions

An example of diverging process:

 $(\mu p.a \rightarrow p) \land a$

The divergence model (Brookes, Roscoe)

CSP semantics is often expressed through a failures set A failure is of the form

[s, X]

where ${\bf s}$ is a trace (sequence of events) and ${\bf X}$ a finite set of events

A failure set must satisfy the following properties:

- ▶ [<>, Ø] ∈ F
- > [s+t,∅]∈F ⇒ [s,∅]∈F
- \succ [s, X] ∈ F \land Y ⊆ X \Rightarrow [s, Y] ∈ F
- > [s, X] ∈ F ∧ [s + <c>, Ø] ∉ F ⇒ [s, X ∪ {c}] ∈ F

Basic CSP syntax

P ::=

- $a \rightarrow Q$ | -- Engages in a, then acts like Q
- Q ∏ R | -- Internal choice
- Q□R | -- External choice
- Q | R | -- Concurrency (E: subset of alphabet)
- $Q \parallel R \parallel --$ Lock-step concurrency (same as $Q \parallel R$)
- $Q \setminus E$ | -- Hiding
- $\mu Q \bullet f(Q)$ -- Recursion

CSP laws in the divergence model (1/2)

```
P \square P \equiv_M P
                     P \square Q \equiv_{\mathcal{M}} Q \square P
           P \square (Q \square R) \equiv_M (P \square Q) \square R
           P \square (Q \sqcap R) \equiv_M (P \square Q) \sqcap (P \square R)
           P \sqcap (Q \square R) \equiv_M (P \sqcap Q) \square (P \sqcap R)
             P \square \text{STOP} \equiv_M P
       (a \to (P \sqcap Q)) \equiv_M (a \to P) \sqcap (a \to Q)
(a \to P) \square (a \to Q) \equiv_M (a \to P) \sqcap (a \to Q)
                     P \sqcap P \equiv M P
                     P \sqcap Q \equiv_M Q \sqcap P
           P \sqcap (Q \sqcap R) \equiv_M (P \sqcap Q) \sqcap R
                     P \parallel Q \equiv_M Q \parallel P
            P \parallel (Q \parallel R) \equiv_{M} (P \parallel Q) \parallel R
           P \parallel (Q \sqcap R) \equiv_M (P \parallel Q) \sqcap (P \parallel R)
(a \to P) \parallel (b \to Q) \equiv_M \text{STOP} if a \neq b
                                 \equiv_M (a \to (P \parallel Q)) \text{ if } a = b
              P \parallel \text{STOP} \equiv_M \text{STOP}
```

(From: Brooks & Roscoe 85)

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CSP laws (2/2)

```
P|||Q \equiv_M Q|||P
          (P|||Q)|||R \equiv_M P|||(Q|||R)
         P|||(Q \sqcap R) \equiv_{\mathcal{M}} (P|||Q) \sqcap (P|||R)
(a \to P) \parallel \mid (b \to Q) \equiv_M (a \to (P \parallel \mid (b \to Q))) \square (b \to ((a \to P) \parallel \mid Q))
             P;(Q;R) \equiv_M (P;Q);R
            \text{STOP} ||| Q \equiv_M Q
               SKIP: Q \equiv_M Q
             STOP; Q \equiv_M STOP
           P; (Q \sqcap R) \equiv_M (P; Q) \sqcap (P; R)
           (P \sqcap Q); R \equiv_M (P; R) \sqcap (Q; R)
           (a \to P); Q \equiv_M (a \to P; Q) if a \neq \checkmark
                (P \mid a) \mid b \equiv_M (P \mid b) \mid a
               (P \setminus a) \setminus a \equiv_M P \setminus a
            (a \to P) \setminus b \equiv_M (a \to P \setminus b) if a \neq b
                             \equiv_M P \setminus b if a = b
            (P \sqcap Q) \setminus a \equiv_{\mathcal{M}} (P \setminus a) \sqcap (Q \setminus a)
```

Non-timed:

- > The \checkmark event (not in Σ): successful termination
- Skip : successfully terminates
- Sequential composition: P ; Q
- ▶ ⊥ : diverging process

Timed:

P / Q: interrupt

- $> P \stackrel{t}{\triangleright} Q$: timeout
- > $a \xrightarrow{!} P$: communicate immediately
- > WAIT t: same as STOP $\stackrel{t}{\triangleright}$ SKIP

V1 = coin.in → ((coke → V1) □ (fanta → V1)) $\stackrel{60}{\triangleright}$ (coin.out $\stackrel{!}{\rightarrow}$ V1)

Some laws no longer hold

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P || STOP = STOP if P \neq \perp
 \perp || STOP = \perp
```

```
(a \rightarrow P) \setminus b = a \rightarrow (P \setminus b) if a \neq b
(a \rightarrow P) \setminus a = P \setminus a
```

A calculus based on mathematical laws

Provides a general model of computation based on communication

Serves both as specification of concurrent systems and as a guide to implementation

One of the most influential models for concurrency work

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