# Eventually Consistent Transactions

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### Goal

- Eventual consistency in a distributed system is nice. It allows temporarily disconnected replicas to remain fully available.
- Find answers to the questions:
  - How to provide consistency guarantees that are as strong as possible without losing lazy consensus?
  - 2. How to effectively **understand and implement** systems that provide these guarantees?

### Outline

- Model Assumptions
- Important Definitions
- Sequential vs. Eventual Consistency
- Revision Consistency

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- Construction and Properties of Revision Diagrams
- **Theorem**: Revision Consistency ⇒ Eventual Consistency
- Conclusion and Future Work

### **Model Assumptions**

- Distributed system.
- Multiple participants (*clients*).
- One logical database, referred to as a Query-Update-Automaton (QUA).
- Clients issue eventually consistent transactions, that cannot fail and never roll back.
- All code runs inside transactions.

### **Model Assumptions**



- This is a logical view of the situation.
- The state of the QUA might be distributed and temporarily inconsistent.

## Query-Update Interface & Automaton

#### Definition

A query-update interface is a tuple (Q, V, U) where

- *Q* is a set of query operations.
- V is a set of values returned by queries.
- *U* is a set of update operations.

#### Definition

A query-update automaton (QUA) for interface (Q, V, U) is a tuple  $(S, s_0)$  together with an **interpretation**, where

- S is a set of states
- s<sub>0</sub> is the initial state
- $q^{\#}$  is an interpretation of query  $q \in Q$  as a function  $S \rightarrow V$
- $u^{\#}$  is an interpretation of command  $u \in Q$  as a function  $S \rightarrow S$

### **Histories**

#### Definition

A history *H* is a **map** that maps each client  $c \in C$  to a finite or infinite **sequence** H(c) of following events:

- $u \in U$  is an **update** issued by the client.
- (q, v) represents a **query** with its **return value**.
- yield **commits** transactions.

Example:	CLIENT #1	CLIENT #2
Linple.	<pre>x := load(a); store(b, x); yield; y := load(b); store(a, y);</pre>	<pre>store(c, 5); yield; i := load(c); store(c, i+2); vield:</pre>
	vield:	, ,

### **Consistency Models**

Sequential Consistency:

"The result of any execution is the same as if the operations of all the processors were executed in some sequential order, while retaining the program order."

Eventual Consistency:

"If no new updates are made to a data object, eventually all accesses will return a consistent value."

### **Enhance History with Additional Orders**



### Sequentially Consistent History

- Find a single partial order < over all events in a given history, with the following properties:
  - Compatibility with program order.
  - Past events are totally ordered.
  - Transactions are atomic.
  - Transactions are executed in isolation.
  - Committed transactions are eventually delivered to all participants.

Sequential consistency **does not** tolerate temporary network partitions!

### **Eventually Consistent History**

- Instead of one partial order, we try to find two:
  - Visibility order <<sub>v</sub>
  - Arbitration order <<sub>a</sub>
- The visibility order defines which events' effects are visible to which other events.
- The arbitration order defines the relative order of past events.

Eventual consistency tolerates temporary network partitions!

### **Eventual Consistency in Related Work**

- In order to arbitrate events, two common approaches exist:
  - Use **timestamps**, actual or logical.
  - Make updates commutative.
- This paper suggests a different approach, which does not require any of the above.
  - Main contribution of the paper.

### Write Stabilization Problem

Alice	Bob	Robinson		
update(); <b>yield;</b>	update(); <b>yield;</b>	update(); yield;		
<pre>Repeat 1000x:     update();     yield; Cannot stabilize!</pre>	<pre>Repeat 1000x:     update();     yield; Cannot stabilize!</pre>	Robinson disconnects! Perform importar update!	) )t	
Solution: Simply order Robinson's update <b>after</b> all the others!				

### **Revision Diagrams**

- A definition of Eventual Consistency does not by itself give guidelines as to how to build a system that is eventually consistent.
- That's why Revision Diagrams are introduced.



### Revisions

- Revisions are logical replicas of the state.
- Clients work with one revision at a time, and can perform operations on it.
- Reconciliation happens during a so-called join operation between two revisions.

### **Revision Diagram: Construction Rules**

• Start with **root vertex** as the only terminal, and then:



### Join Condition

In order for revision diagrams to be eventually consistent, the join condition needs to be satisfied.

#### Definition

Join condition: The vertex that forked the joined revision must reach the *join* vertex

 This establishes important validity conditions and is needed for the proof of the upcoming theorem.

### Example of non-satisfied Join Condition



## **Graph Properties of Revision Diagrams**



- Vertices of the same revision have the same x-coordinate.
- Fork vertices spawn new revisions to the right.
- Join vertices merge revisions coming from the right.

### Effects of the Vertices

#### Definition

For any vertex *x*, we let the **effect** of *x* be a function  $x^{\circ}: S \rightarrow S$  defined inductively as follows:

- If x is a start, fork or query vertex, there is no effect.
- If x is an update vertex for some update operation, then the effect is that update.
- If x is a join vertex, then the effect is the composition of all effects in the joined revision.

### **Update Effects**



### Revision Diagrams $\Leftrightarrow$ Histories



### **Requirements of Witness Diagrams**



- Query events match the pathresult.
- Successive non-yield operations of the same client are connected by a vertical edge.
- The beginning of a transaction must be reachable from the end of the previous transaction of the same client.

### **Neglected Vertices**

#### Definition

A vertex x is **neglected**, if there exists an **infinite number** of vertices y such that there is no path from x to y.

 This would mean that the operation associated to this vertex could starve, i.e. could not eventually be delivered.





#### Theorem

Let H be a history. If there exists a witness diagram for H such that no committed events are neglected, then H is eventually consistent.

- In the paper, a **proof** is included.
- Note that the converse is not true, i.e. if *H* is eventually consistent, there might not exist a witness diagram for it.

### **System Implementation**

### Two eventually consistent systems might look like:

#### Single Synchronous Server Model

- Single server
- Multiple clients
- The server can spawn clients
- Clients can join the server
- Transactions are committed by clients by joining and forking again.

Pro:Simple and intuitiveContra:Clients block if they<br/>have no connection

#### Server Pool Model

- Multiple servers
- Multiple clients
- Servers can spawn clients
- Clients can join servers
- Servers can join servers
- Need vector clocks to ensure the join condition

Pro:	Better scalability; No blocking
Contra:	Complex

### Contribution

 Unique use of *revision diagrams* to determine **both** arbitration and visibility.

- Revision Diagrams are simple to construct and can be visualized easily.
  - This eases system implementation and understanding.

### **Future Work and Impact**

- Extend study of this programming model.
- Are there stronger consistency guarantees possible for subclasses of eventual consistent transactions?

- This work had an impact on:
  - Cloud types for eventual consistency<sup>1</sup>
    - Proposes the use of specialized cloud data types.
  - Library abstraction for C/C++ concurrency<sup>2</sup>
    - Proposes a criterion for sound library abstraction in the new C11 and C++11 memory model.
      - <sup>1</sup> Microsoft Research
      - <sup>2</sup> Mark Batty, Mike Dodds, Alexey Gotsman