

# Separation Logic, Abstraction and Inheritance

M. Parkinson, G. Bierman, in *Proc. POPL*, 2008

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Research Topics in Software Engineering

- ① From Separation Logic to Inheritance
- ② Beyond Separation Logic
- ③ What About Invariants?

- 1 From Separation Logic to Inheritance
- 2 Beyond Separation Logic
- 3 What About Invariants?

- Extension of Hoare Logic
- Models heap manipulation
- Local reasoning: separate heap into **disjoint parts**
- No abstraction (modules, classes, dynamic method binding)

$$\{P\}C\{Q\}$$
$$\{Precondition\}Code\{Postcondition\}$$

# Separation Logic: Specification and Program Constructs

## Specifications

- Points to predicate:  $i \mapsto x$
- \* conjunction:  $i \mapsto x * j \mapsto y$

## Program

- Heap allocation:  $\text{cons}(x)$
- Heap lookup:  $i = [x]$
- Heap assignment:  $[x] = i$
- Heap deallocation:  $\text{dispose}(x)$

## Frame Rule

$$\frac{\{P\}C\{Q\}}{\{P * R\}C\{Q * R\}}$$

Provided: free variables of  $R$  are not modified in  $C$

- Aliasing control
- Local reasoning

Challenges of object-oriented languages:

- Heavy heap usage: object references
- Inheritance and dynamic dispatch

## Separation logic

- Is a good framework for heap control
- Needs extension to support inheritance

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## 3 extensions

- 1 Abstract Predicate Families to abstract data types
- 2 Static and Dynamic method specifications for static or dynamic method calls
- 3 Verification rules: method body is verified exactly once

## Example

```
class Cell {  
    int val;  
  
    public Cell(){}  
  
    public virtual void set(int x)  
    {this.val = x;}  
  
    public virtual int get()  
    {return this.val;}  
}
```

```
class ReCell: Cell {  
    int back;  
  
    public Cell(){}  
  
    public override void set(int x)  
    {this.back = this.Cell::get();  
    this.Cell::set(x);}  
  
    public inherit int get();  
    public virtual void undo(){...}  
}
```

## Extension 1: Abstract Predicate Family

- Abstract predicate describe abstract data types
- Class hierarchy gives a family of abstract predicates, one for each class
- Predicates accessible within the class hierarchy, predicate definition accessible within the class

### Example

Family  $Val(x, v)$ :

$$Val_{Cell}(x, v) \hat{=} x.val \mapsto v$$

$$Val_{ReCell}(x, v, b) \hat{=} Val_{Cell}(x, v) \wedge x.back \mapsto b$$

Note: variable argument numbers are compensated by existential quantifiers

- Two types of specifications: static ( $\{S_C\}_\{T_C\}$ ) and dynamic ( $\{P_C\}_\{Q_C\}$ ), for static and dynamic dispatch

### 4 elementary verifications

- **Body verification:**  $\{S_C\}_\{T_C\}$  *method body*  $\{T_C\}$
- **Dynamic dispatch:**  $\{S_C\}_\{T_C\}$  stronger than  $\{P_C\}_\{Q_C\}$
- **Behavioral subtyping:** with  $D <: C$ ,  $\{P_D\}_\{Q_D\}$  stronger than  $\{P_C\}_\{Q_C\}$
- **Inheritance:** with  $D <: C$ ,  $\{S_C\}_\{T_C\}$  stronger than  $\{S_D\}_\{T_D\}$

## Extension 3, Verifying Methods: `Cell::set(int x)`

### Specifications

- Dynamic:  $\{Val(this, \_)\} \_ \{Val(this, x)\}$
- Static:  $\{Val_{Cell}(this, \_)\} \_ \{Val_{Cell}(this, x)\}$

### Verification: method implemented in the base class

- Body verification:

$$\{Val_{Cell}(this, \_)\} this.val = x; \{Val_{Cell}(this, x)\}$$

- Dynamic dispatch:

$$\begin{aligned} & \{Val_{Cell}(this, \_)\} \_ \{Val_{Cell}(this, x)\} \\ & \Rightarrow \{Val(this, \_)\} \_ \{Val(this, x)\} \end{aligned}$$

## Extension 3, Verifying Methods: `ReCell::set(int x)`

### Specifications

- Dynamic:  $\{Val(this, v, \_)\} \_ \{Val(this, x, v)\}$
- Static:  $\{Val_{ReCell}(this, v, \_)\} \_ \{Val_{ReCell}(this, x, v)\}$

### Verification: overridden method

- Behavioral subtyping:

$$\begin{aligned} & \{Val(this, v, \_)\} \_ \{Val(this, x, v)\} \\ & \Rightarrow \{Val(this, \_)\} \_ \{Val(this, x)\} \end{aligned}$$

- Dynamic dispatch
- Body verification

## Extension 3, Verifying Methods: ReCell::get()

### Specifications

- Dynamic:  $\{Val(this, v, o)\} \_ \{Val(this, v, o) * ret = v\}$
- Static:  $\{Val_{ReCell}(this, v, o)\} \_ \{Val_{ReCell}(this, v, o) * ret = v\}$
- Static for Cell:  $\{Val_{Cell}(this, v)\} \_ \{Val_{Cell}(this, v) * ret = v\}$

### Verification: inherited (not overridden) method

- Inheritance:

$$\begin{aligned} & \{Val_{Cell}(this, v)\} \_ \{Val_{Cell}(this, v) * ret = v\} \\ \Rightarrow & \{Val_{ReCell}(this, v, o)\} \_ \{Val_{ReCell}(this, v, o)\} \end{aligned}$$

- Behavioral subtyping
- Dynamic dispatch

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- Invariant: explicit consistency criterion on an object
  - When does it hold or not? How does an object tell that to a client?
- 
- Drossopoulou et al., in *ECOOP*, 2008
  - Spec#, Barnett et al., in *Proceedings of CASSIS*, 2005

## Example

```
class DCell: Cell {  
    public DCell(){}  
  
    public override void  
        set(int x)  
    {this.Cell::set(2 * x);}  
}
```

- Not a behavioral subtype: “copy-and-paste” inheritance
- Forbidden in invariant-based approaches
- With separation logic:

$$Val_{DCell}(x, v) \hat{=} false$$

$$DVal(x, v) \hat{=} Val_{Cell}(x, v)$$

works fine: DCell is not a (behavioral) subtype of Cell for the logic.

## Framework

- More expressive than most other approaches
- Requires more annotation: this can be automated
- Cannot use first-order SMT solvers
- Has been extended to a Java verifier (jStar, Distefano et al., in *OOPSLA*, 2008)

## Article

- Self-contained, no other article required if you know separation logic
- Well explained: formalism, intuition, examples
- Gives an elegant solution in an elegant form

4 Formal Separation Logic Definitions

5 Bibliography

# Separation Logic Definitions: Stack and Heap

## Definition (Stack)

$$S \hat{=} \text{Variables} \rightarrow \text{Values}$$

## Definition (Heap)

$$H \hat{=} \text{Locations} \rightarrow \text{Values}$$

## Definition (Program State)

$$(S, H, I)$$

- $I$ : auxiliary variables stack

## Definition (points to)

$$(S, H, I) \models E \mapsto E' \hat{=} \text{dom}(H) = \{[E]_{S,I}\} \\ \wedge H([E]_{S,I}) = [E']_{S,I}$$

## Definition (star)

$$(S, H, I) \models P * Q \hat{=} \exists H_1, H_2. H_1 * H_2 = H \\ \wedge (S, H_1, I) \models P \wedge (S, H_2, I) \models Q$$

## Definition (Frame Rule)

$$\frac{\vdash \{P\}C\{Q\}}{\vdash \{P * R\}C\{Q * R\}}$$

Provided:  $\text{modified}(C) \cap \text{FV}(R) = \emptyset$

- M. Barnett, K. R. M. Leino and W. Schulte. “The Spec# Programming System: An Overview”. In *Proceedings of CASSIS*, 2005
- D. Distefano and M. Parkinson “jStar: towards practical verification for java”, in *OOPSLA* 2008
- S. Drossopoulou, A. Francalanza, P. Müller and A. J. Summers. “A Unified Framework for Verification Techniques for Object Invariants”. In *ECOOP* 2008