

Enabling the Runtime Assertion Checking  
of Concurrent Contracts  
for the Java Modeling Language

by Wladimir Araujo, Lionel C. Briand, Yvan Labiche

CCC Seminar Talk

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- [4] Antonio Carzaniga et al. “Cross-checking Oracles from Intrinsic Software Redundancy”. In: ICSE 2014. Hyderabad, India: ACM, 2014, pp. 931–942.
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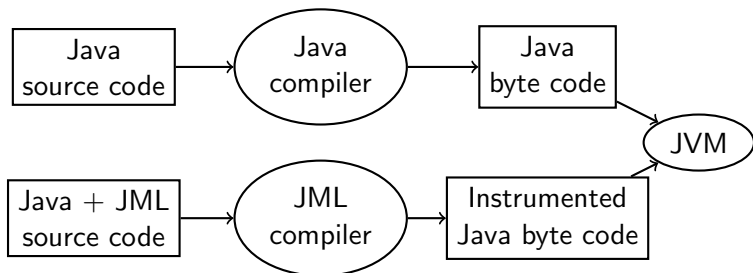
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## Design by Contract in a nutshell

Theory: correct program + DbC  $\iff$  correct program

Run-time:

Sequential: regular  $\equiv$  instrumented

Concurrent: *execution time affects execution paths*

## How to restore equivalence?

- Interference

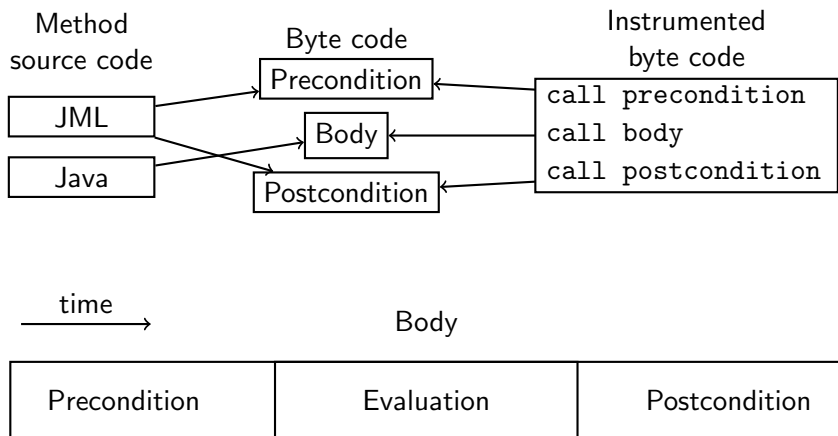
Objects involved in contracts may be changed before/after or during execution of a method

- Locking-related properties

Deadlocks

- Specification of thread-safety properties in presence of inheritance

Thread-safety predicates may become meaningless in descendants



# Interference *Example: Linked queue*

```
/* @ public normal_behavior
3   @ ensures \result <==> head.next == null */
public boolean isEmpty () {
1   synchronized (head) {

2   return head.next == null;
   }}
```

...	...	"make list empty"	head.next == <b>null</b>
T1	1'	lock (head)	[head]
T1	2	<b>result</b> = (head.next == <b>null</b> )	[head], <b>result</b> == <b>true</b>
T1	1''	unlock (head)	<b>result</b> == <b>true</b>
T2	...	insert (v)	head.next != <b>null</b>
T1	3	<b>result</b> <==> head.next == <b>null</b>	<i>Postcondition violation!</i>

# Interference *Example: Linked queue*

```

/* @ public normal_behavior
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public boolean isEmpty () {
1   synchronized (head) {
    // @ ensures_safepoint:
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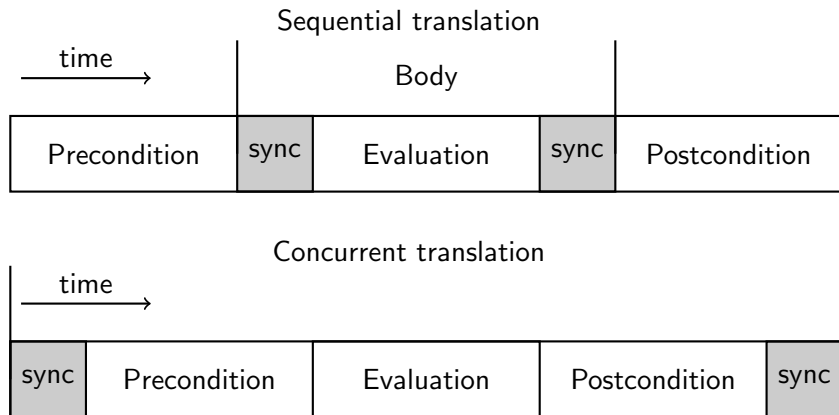
...	...	"make list empty"	head.next == <b>null</b>
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T1	2	<b>result =</b> (head.next == <b>null</b> )	[head], <b>result == true</b>
T1	1''	unlock (head)	<b>result == true</b>
T2	...	insert (v)	
T1	3	<b>result &lt;==&gt;</b> head.next == <b>null</b>	



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T1	3	<b>result</b> <==> head.next == <b>null</b>	[head], <i>Postcondition OK</i>
T1	1''	unlock (head)	<b>result</b> == <b>true</b>



<b>Mechanism</b>	<b>Specification</b>	<b>Implementation</b>
Safepoints	requires ensures	requires_safepoint ensures_safepoint
Wait condition	when	commit
Thread safety	requires_thread_safe ensures_thread_safe	—

## Scope

- Safepoints: internal state
- Thread safety: external state

Mechanism	Specification	Implementation
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## Scope

- Safepoints: internal state
- Thread safety: external state

**Thread safety + Safepoints = No Interference**

## Syntax

$$\text{lock\_order } lock1 < lock2$$

$$\text{lock\_order } lock1 \leq lock2$$

## Semantics

Acquisition order	<	<=
<i>lock1</i> before <i>lock2</i>	true	true
<i>lock1</i> only	true	true
<i>lock2</i> before <i>lock1</i>	false	false
<i>lock2</i> only	false	false
neither <i>lock1</i> nor <i>lock2</i>	false	true

## Monitoring

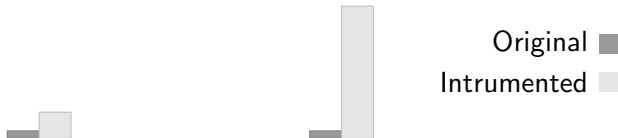
At every lock acquisition point

Before actually attempting to acquire a lock (to prevent deadlocks)

- Setup: Router driver of Juniper's E-series routers, 520 000 active subscribers, 1 500 transactions per second
  - 54 classes
  - 33 509 LOC
  - 34% concurrent behavior
- Measurement

Heap consumption: 3.47

CPU load: 17.5



Performance ratio between production and instrumented versions is **constant**.

## Analysis of behavior:

- Standard test suite
  - 2 hours, no contract violations
- Faults introduced from Juniper's defect database
  - Instrumentation to print errors instead of assertion violations
  - Reproduced all 139 functional and concurrent faults
- Influence of instrumentation on thread interleavings
  - No additional locks
    - Safepoint evaluation (inside synchronized)
    - Commit points for wait conditions (inside synchronized)
    - Locking predicates (use thread-local objects in pre- and post-states)
  - Limited locking
    - `ConcurrentHashMap` optimized for concurrent access
    - Writes only in pre- and post-states of methods with `requires_/ensures_thread_safety`
    - Reads rarely acquire locks

<b>Property</b>	<b>Concurrent JML</b>	<b>SCOOP</b>
Syntax	> 10 keywords	<i>separate</i>
Internal state	Safepoints	No data races
External state	Thread-safety	Controlled arguments
Wait conditions	Explicit	Separate calls in preconditions
Synchronization	Explicit locking	Controlled arguments
Deadlock avoidance	Lock order	Partial: controlled arguments



For further discussion

- What is allowed between method entry and `requires_safe_point`?
- Blocks `concurrent_behavior` are combined using conjunction. What about modularity?
- What feature of concurrent JML would be nice to have in SCOOP?
- What can be improved or simplified in concurrent JML?
- Does lock order specification prevent from deadlocks?