

Yanyan Jiang Tianxiao Gu Chang Xu Xiaoxing Ma Jian Lu

Cache Guided Deterministic Replay for Concurrent Java Programs

What is it about?

- Concurrent programs are difficult to debug.
- Use deterministic replay
- Search-based
 - Small log, small record cost, incomplete
 - Best-effort exhaustive state space search
- Order-based
 - Record dependences among key events: R/W, (un)lock
 - Huge logs: STRIDE 30MB/s \rightarrow Performance degradation
 - Easy replay

CARE

- Cache guided deterministic replay
- Key Idea: Take advantage of thread locality
 - i.e. no need to record access to same variable by same thread twice.
- Only record dependencies among different Threads
- Cache miss \rightarrow other thread did access same variable
- Cache miss detected by value prediction cache

No cache miss

<u>T1</u> x = 1; y = 2;

z = 2;

<u>T2</u>

VPC:	Real cache:
x = 1	x = 1
y = 2	y = 2

<u>T1</u> x = 1; y = 2;

x = 2;

<u>T2</u>

VPC:	Real cache:
x = 1	x = Invalid
y = 2	y = 2

VPC:	Real cache:		
x = 2	x = 2		

Cache miss detected

<u>T1</u> x = 1; y = 2;

x = 2;

<u>T2</u>

VPC:	Real cache:
x = 1	x = 2
y = 2	y = 2

VPC:	Real cache:
x = 2	x = 2

<u>T1</u> x = 1; y = 2;

<u>T2</u>

x = 1;

VPC:	Real cache:
x = 1	x = invalid
y = 2	y = 2

VPC:	Real cache:
x = 1	x = 1

Cache miss not detected

<u>T1</u> x = 1; y = 2;

read x;

VPC:	Real cache:
x = 1	x = 1
y = 2	y = 2

VPC:	Real cache:
x = 1	x = 1

<u>T2</u>

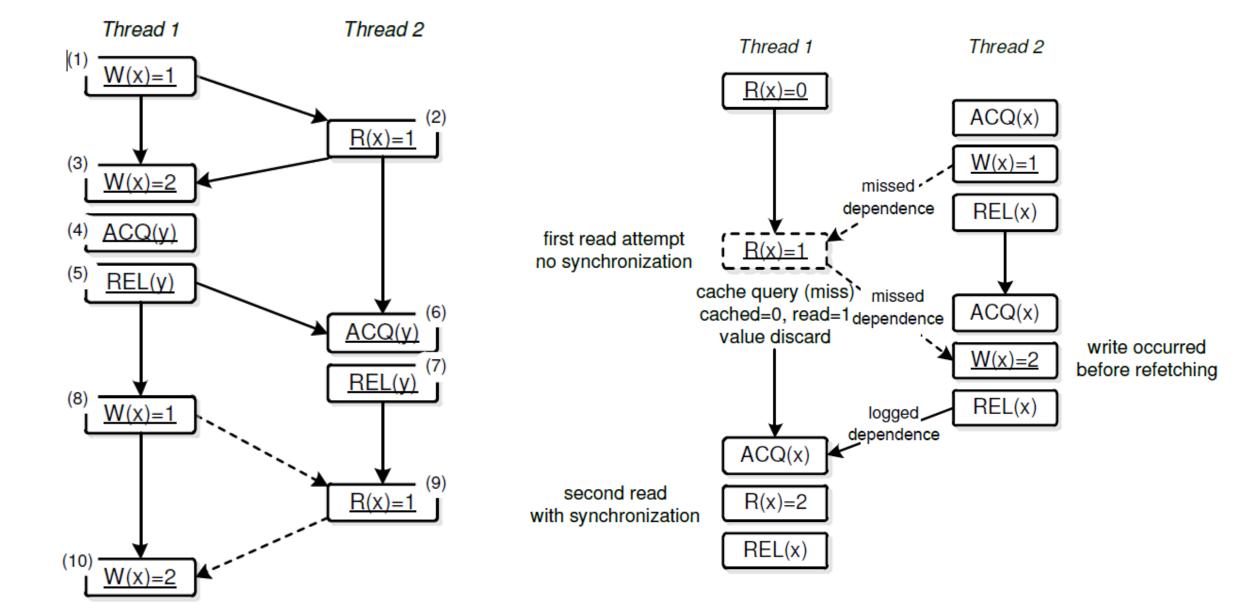


Figure 2: Illustration of refetching

Figure 1: Illustration of missing dependences

Algorithm 1: read

 $d \leftarrow heap(v)$ if cache(v) \neq d then synchronized v $d \leftarrow heap(v)$ $H \leftarrow H \cup (last(v),r)$ $G \leftarrow G \cup \{r\}$ $last(v) \leftarrow r$ $cache(v) \leftarrow d$

G: set of read actions with cache miss
H: inter thread dependences
r = <tid,read,v,uniqueld>

Algorithm 2: write

synchronized v heap(v) \leftarrow d if last(v).t \neq t then H \leftarrow H \cup (last(v),w) last(v) \leftarrow w cache(v) \leftarrow d G: set of read actions with cache missH: inter thread dependencesw = <t, write, v, uniqueld>

Algorithm 3: lock

acquire(v) if last(v).t \neq t then $H \leftarrow H \cup (last(v), l)$ $last(v) \leftarrow w$ G: set of read actions with cache missH: inter thread dependencesw = <t, acquire, v, uniqueld>

Cache Organization

• Big cache

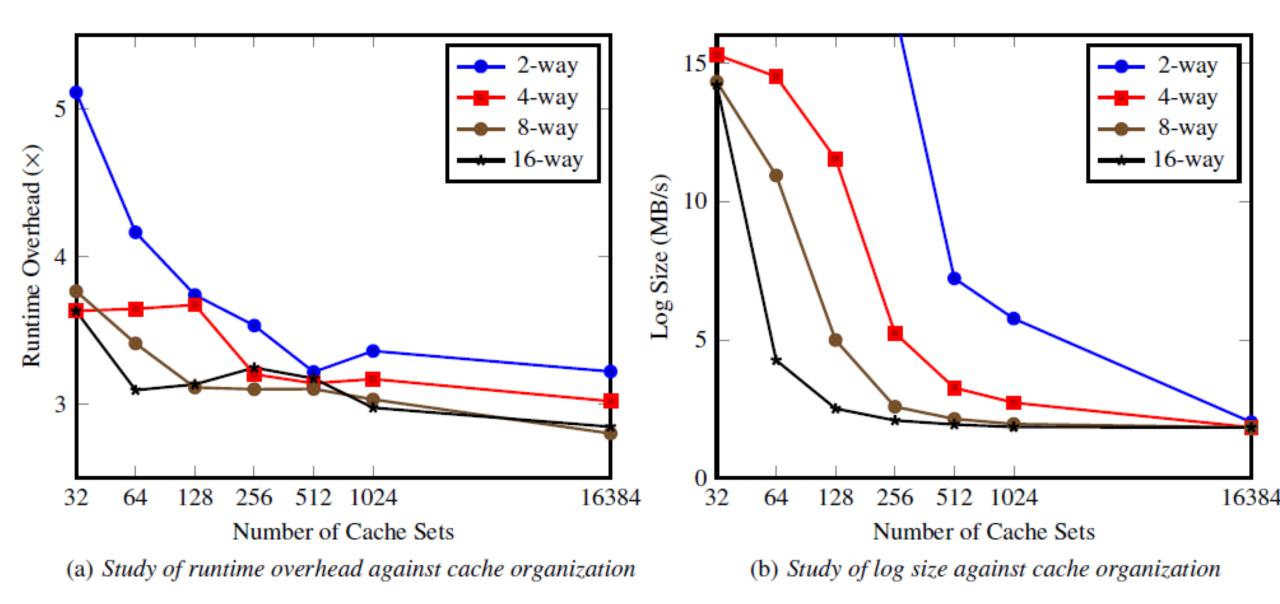
- Less unnecessary cache misses \rightarrow smaller log
- Disables the garbage collection mechanism \rightarrow drains memory

• Small cache

Unnecessary cache misses

• Optimal cache

- Efficient updates and queries
- Moderate memory consumption
- High cache hit rate



Heuristics to still get SC replay

- Try to schedule read actions first
 - If desired value is inconsistent with the one in the heap suspend thread
 - Immediately after desired value is written resume
- Add sequence number to groups of variables
 - Sequence numbers define dependences between variables

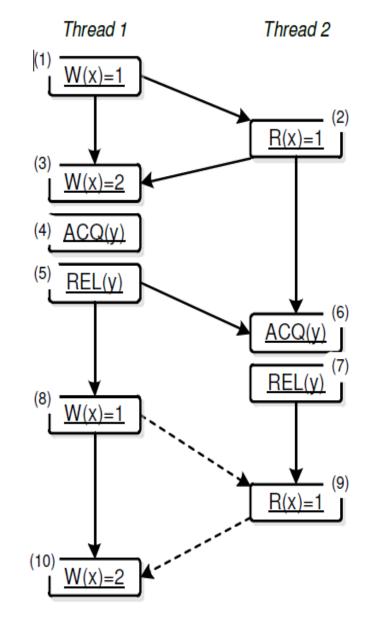


Figure 1: Illustration of missing dependences

Performance

Table 1: Comparison of CARE and LEAP under benchmark programs

Benchmark	CARE			LEAP [18]		
Бенсптатк	Overhead (X)	Log Size (/s)	Unordered (#)	Resolved (?)	Overhead (×)	Log Size (/s)
Avrora	1.52	2.18MB	23K	Y	9.48	24.3MB
Batik	1.49	1.51KB	0	Y	3.77	2.32KB
H2	18.5	24.2MB	0	Y	62.8	27.4MB
Lusearch	3.41	6.53MB	0	Y	9.01	46.0MB
Sunflow	64.9	886MB	0	Y	389	6029MB
Tomcat	4.76	7.80MB	15	Y	11.9	23.5MB
Xalan	7.18	13.6MB	0	Y	12.2	143MB
Tsp	2.79	1.84MB	0	Y	111	570MB
Moldyn	11.9	24.1MB	0	Y	50.5	303MB

Performance

Table 2: Comparison of CARE and Stride with normalized values

Benchmark	CARE		Stride [37]		
Denchmark	Overhead	Log Size	Overhead	Log Size	
Avrora	16.0%	8.97%	54.0%	36.4%	
Batik	39.5%	65.1%	50.0%	34.9%	
H2	29.5%	88.3%	29.8%	23.9%	
Lusearch	37.9%	14.2%	34.7%	30.0%	
Sunflow	16.7%	14.7%	38.5%	9.17%	
Tomcat	40.0%	33.2%	64.3%	34.6%	
Xalan	59.2%	9.52%	19.0%	23.1%	
Tsp	2.51%	0.32%	9.36%	7.18%	
Moldyn	23.8%	7.94%	1.32%	0.71%	

Conclusion

- CARE records only inter-thread dependencies
- Takes use of cache: cache miss = dependency
- Good performance: small log, low overhead